

# A Liquid–Solid Two-phase Flow Computational Fluid Dynamic Modelling of the Operational Characteristics Effects on the Cleaning Time of a Circulating Flow Loop

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## ABSTRACT

Flow loops and computational fluid dynamics are the main research approaches for resolving the hole-cleaning problems. Cutting transport phenomena can be considered as a Computational Fluid Dynamic (CFD) model by using Eulerian assumptions for the turbulent liquid–solid flow in concentric annuli. The effect of time along with the main operational characteristics on the hole-cleaning phenomena is not negligible but recent studies have had paid little attention to it. Poor near bit cleaning causes many problems such as bit balling, decline in the rate of penetration, pipe sticking, etc. In addition to the effect of inclination, drill pipe rotary speed, cutting size, nozzle velocity and fluid viscosity as well as the effect of the bit nozzle arrangement on the cutting transport process were discussed. The results demonstrate that at a critical inclination angle of 30 degrees the cutting transport is inefficient. For all sections, the effect of drill pipe rotary speed was negligible at high velocities. In the horizontal section, at low flow rates and high drill pipe rotation speeds, Newtonian viscous fluids or water has no effect on the time needed for initial hole-cleaning but by removing the drill pipe rotation speed in similar conditions, a dramatic influence on time is observed. In inclined annuli, increasing the cuttings size and decreasing the nozzle velocity result in having no cutting in the output. Under critical inclination (30 degrees) the effect of the nozzle angle pattern on the hole-cleaning time is negligible. However, for a vertical annulus, the nozzle angle significantly influences the cutting transport. The best performance is obtained when the nozzle angle was perpendicular to the drill pipe axes.

## KEYWORDS

Two-phase flow, flow characteristics, CFD, jetting flow.

## 1. Introduction

The cutting transport phenomenon is one of the main important subjects in drilling of horizontal and extended reach wells. Inadequate cutting transport is associated with many problems such as lowering the drilling performance, grinding of cuttings into fines at bit, difficulties in mud and solid control maintenance, increasing the equivalent circulating density (ECD), increasing the mechanical torque and drag, over pull on drilling string and unnecessary back reaming and fishing operation.<sup>1,2,3</sup> Therefore, the bottom hole has been a concern for drilling operations which is resulted in excessive well construction expenditure.<sup>4</sup>

Bottom Hole Assembly (BHA), drill pipe rotary speed (RPM), flow rate, rate of penetration (ROP) and drilling fluid properties and inclination are the common factors that can be manipulated and controlled to gain a proper hole.<sup>5</sup> Since the investigation and study of the effective drilling characteristics on the bottom hole on a drilling rig is costly, researchers have attempted to study this subject with a variety of approaches such as flow loops and Computational Fluid Dynamics (CFD).<sup>6,7</sup> Usually the cutting concentration, mean bed height and the length of the bed are the main variables that are traced for hole-cleaning efficiency across the annulus.<sup>8,9</sup>

Cutting transport phenomenon can be considered as a liquid–

solid system in CFD modelling.<sup>10</sup> Simulations are validated based on the experimental data from the flow loops.<sup>11</sup> Many parameters can be considered in simulations such as collisional models,<sup>4,12</sup> drag models,<sup>2,13</sup> aggregation,<sup>14</sup> restitution coefficient,<sup>15</sup> specular coefficient,<sup>16</sup> sphericity,<sup>17</sup> and the mesh size effect.<sup>18</sup>

In this study, cutting transport phenomena is considered as a CFD model using Eulerian assumptions for the turbulent liquid–solid flow in a concentric annulus. In reality, it was not a good assumption for a long annulus but it helps to have a good sense about the cleaning process time. The first step was the validation of a model built based on the dimension of our experimental setup. The effect of the jet velocity and the nozzle angle (with respect to the drill pipe axes), inclination, viscosity, rotary speed and the cutting size are investigated on the particle removal in the annulus. The initial mass of cuttings at the bottom of the annulus was cleaned by the fluid flow. In our previous work,<sup>19</sup> the critical cleaning inclination at which the cutting transport was inferior was been found to be 30 degrees.

## 2. Materials and Methods

This work describes a simulation model built in ANSYS Fluent, together with an experimental setup to study the effect of key parameters such as time, flow rate, cuttings size, etc., on wellbore cleaning in simulated horizontal, vertical and inclined well sections.

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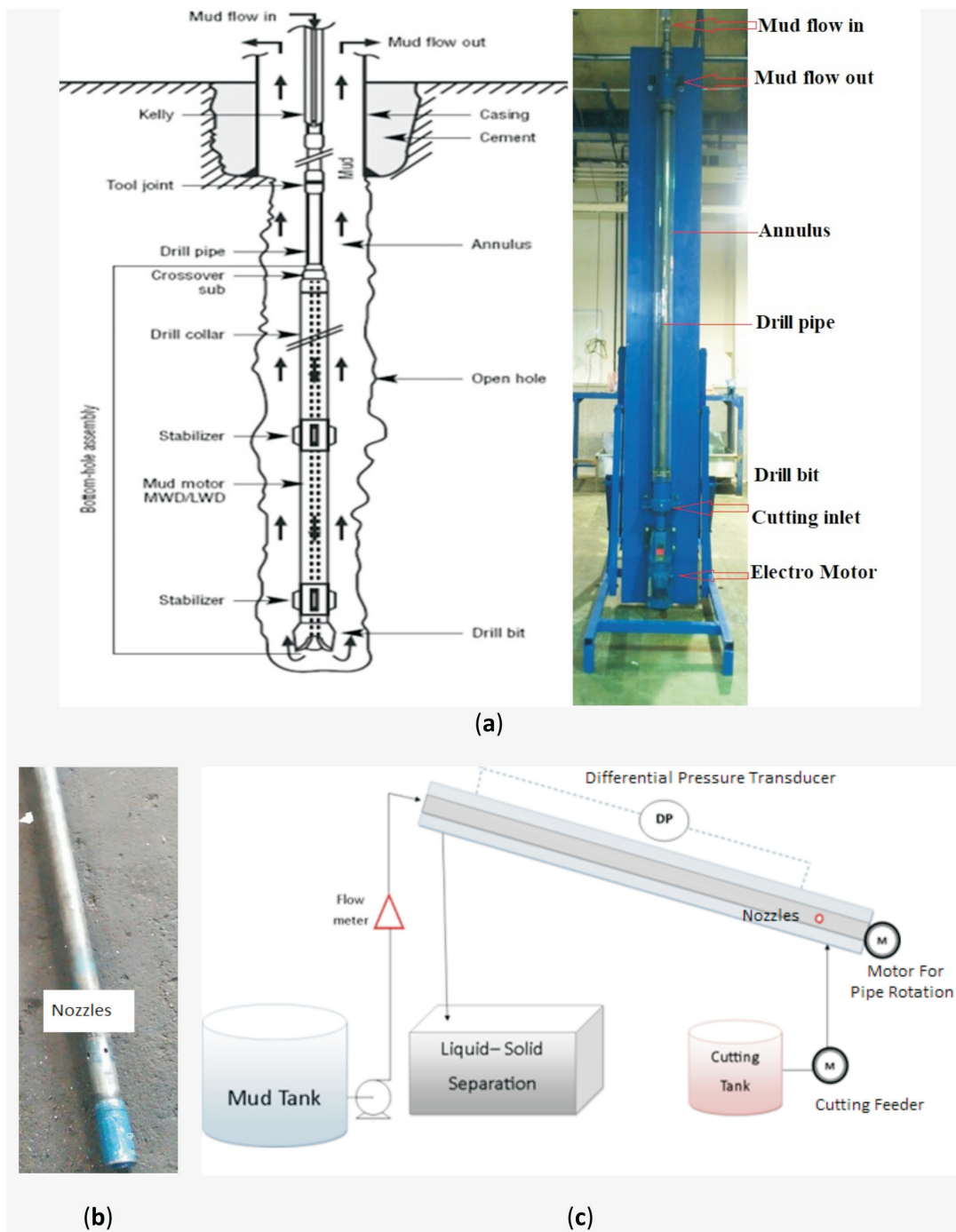


## 2.1. Experimental Flow loop

A flow loop was designed and developed providing a variety of options for controlling test settings, i.e. properties of the annulus, drilling fluid, cuttings, the drill string, temperature and pressure, see Fig. 1a. The annulus was an acrylic tubing with a length and internal diameter of 220.0 cm and 9.0 cm, respectively. Increasing the length of the flow loop not only increased the mesh number and consequently, the simulation time, but also caused some limitation in the inclination range. The inner stainless steel pipe had an outside diameter of 4.3 cm and contained four nozzles with an internal diameter of 0.8 cm. The nozzles were attached on the body of the pipe as shown in Fig. 1b. The inner pipe was connected to an AC motor with a shaft and gear-

box and the rotary speed was controlled by an inverter. The cuttings were injected into the annulus at different rates through a designated inlet. The inclination was also adjusted with two arms from a vertical to a horizontal position. A centrifugal pump was used to inject the fluid into the string and the flow rate was controlled with a flow meter and a bypass system which was installed between pump and flow loop. At the output, a screen was used to collect the cuttings. A mixer was used to prepare the drilling fluid and a differential pressure (DP) transducer recorded the pressure drop in the annulus as indicated in Fig. 1c.

The circulating flow loops mechanism was similar to the drilling operation with minor modifications to suite the laboratory conditions. First, the length of the flow loop seemed a bit small



**Figure 1** (a) Flow Loop sketch and its similarity with a real well. Four nozzles (b) and cutting inlet were located on the right-hand side and one outlet was located on the left side. The drilling fluid was pumped through the drill pipe and then came into the annulus with the nozzles to remove the initial cuttings that were injected through the cutting inlet (c).

for a horizontal or inclined flow. Second, the jet from the four nozzles had a strong effect on the cuttings transport in the present setup. The jetting nozzles were placed at a 7.5 cm distance from the origin. Third, in the drilling operation, the nozzle size was usually optimized based on maximizing the jet impact force or hydraulic horse power, but the pattern of placement was not seen in this setup because of using a centrifuge pump instead of triplex pumps.

## 2.2. CFD Method

The flow loop model was generated with Gambit software used for CFD modelling. The model materials were sand and water. The solver in ANSYS Fluent was pressure-based for absolute velocity formulation in the transient flow. An Eulerian–Eulerian two-phase flow for granular cuttings was selected with a standard k- $\epsilon$  and a standard wall function with mixture multi-phase model.

### 2.2.1. Governing Equations

With merging Eulerian–Eulerian sub-models with the kinetic theory of granular flow,<sup>20,21</sup> the governing equations are presented in this section.

The continuity equation for the solid phase can be written as Equation 1:

$$\frac{\partial}{\partial t}(\alpha_s \rho_s) + \nabla \cdot (\alpha_s \rho_s \mathbf{v}_s) = 0 \quad (1)$$

The momentum equation for the solid phase is:

$$\frac{\partial}{\partial t}(\alpha_s \rho_s \mathbf{v}_s) + \nabla \cdot (\alpha_s \rho_s \mathbf{v}_s \mathbf{v}_s) = -\alpha_s \nabla p + \nabla \cdot \bar{\bar{\tau}}_s - \nabla P_s + \alpha_s \rho_s \mathbf{g} - \beta_{fs}(\mathbf{v}_s - \mathbf{v}_f) \quad (2)$$

The fluctuation energy of the solid particles (granular temperature) is written as:

$$\frac{3}{2} \left[ \frac{\partial}{\partial t}(\alpha_s \rho_s \Theta_s) + \nabla \cdot (\alpha_s \rho_s \mathbf{v}_s \Theta_s) \right] = \left( -p_s \bar{\bar{I}} + \bar{\bar{\tau}}_s \right) : \nabla \mathbf{v}_s + \nabla \cdot (k_{\Theta_s} \nabla \Theta_s) - \gamma_{\Theta_s} - 3\beta_{fs} \Theta_s \quad (3)$$

The constitutive equations used for the Euler–Euler model are<sup>22,23,24</sup>:

Liquid phase stress tensor:

$$\bar{\bar{\tau}}_f = \alpha_f \mu_f \left[ \nabla \mathbf{v}_f + (\nabla \mathbf{v}_f)^T \right] - \frac{2}{3} \alpha_f \mu_f \nabla \cdot \mathbf{v}_f \bar{\bar{I}} \quad (4)$$

Solid phase stress tensor:

$$\bar{\bar{\tau}}_s = \alpha_s \mu_s \left[ \nabla \mathbf{v}_s + (\nabla \mathbf{v}_s)^T \right] + \alpha_s \left( \lambda_s - \frac{2}{3} \mu_s \right) (\nabla \cdot \mathbf{v}_s) \bar{\bar{I}} \quad (5)$$

Solid shear viscosity:

$$\mu_s = \mu_{s,\text{collision}} + \mu_{s,\text{kinetic}} + \mu_{s,\text{frictional}} \quad (6)$$

where

$$\mu_{s,\text{collision}} = \frac{4}{5} \alpha_s \rho_s d_s g_{ss} (1 + e_{ss}) \sqrt{\frac{\Theta_s}{\pi}} \quad (7)$$

$$\mu_{s,\text{kinetic}} = \frac{10 \rho_s d_s \sqrt{\Theta_s \pi}}{96 \alpha_s g_{ss} (1 + e_{ss})} \left[ 1 + \frac{4}{5} \alpha_s g_{ss} (1 + e_{ss}) \right]^2 \quad (8)$$

$$\mu_{s,\text{frictional}} = \frac{P_s \sin \theta_s}{2 \sqrt{I_{2D}}} \quad (9)$$

Solid bulk viscosity:

$$\lambda_s = \frac{4}{3} \alpha_s \rho_s d_s g_{ss} (1 + e_{ss}) \sqrt{\frac{\Theta_s}{\pi}} \quad (10)$$

Collision energy dissipation:

$$\gamma_{\Theta_s} = \frac{12(1 + e_{ss}^2) g_{ss}}{d_s \sqrt{\pi}} \rho_s \alpha_s^2 \sqrt{\Theta_s^3} \quad (11)$$

Solid pressure:

$$P_s = \alpha_s \rho_s \Theta_s + 2 \rho_s (1 + e_{ss}) \alpha_s^2 g_{ss} \Theta_s \quad (12)$$

Radial distribution function:

$$g_s = \left[ 1 - \sqrt[3]{\frac{\alpha_s}{\alpha_{s,\text{max}}}} \right]^{-1} \quad (13)$$

where  $\alpha_s$  is the solid volume fraction and  $\alpha_{s,\text{max}}$  is the maximum packing limit.<sup>25</sup>

And the drag coefficient  $C_d$  is:

$$C_d = \frac{24}{\text{Re}_s} (1 + 0.15 \text{Re}_s^{0.687}), \text{Re}_s \leq 1000 \quad (14)$$

$$C_d = 0.44, \text{Re}_s \geq 1000 \quad (15)$$

### 2.2.2. Model Assumptions

The flow loop model was generated with Gambit software to be used in CFD modelling. The model materials are sand and water. The solver in ANSYS Fluent was pressure-based for absolute velocity formulation in the transient flow. An Eulerian–Eulerian two-phase flow for granular cuttings was selected with a standard k- $\epsilon$  and a standard wall function with mixture multi-phase model. The plexy wall was stationary with standard roughness and no-slip condition for solids. The roughness constant was 0.5. The drill pipe was a moving wall with 11.5 rad s<sup>-1</sup> rotary speed. The k- $\epsilon$  turbulent model has some limitations for the near wall condition. In this study, an effort was made to neglect these defects with an attempt to  $y^+$  diagram. Table 1 shows the related cutting properties in the model.

Solid phase shear bulk viscosity was obtained through applying the kinetic theory to granular flows. Frictional viscosity for modelling the granular flow was also available. The fluid was water with 998.2 kg m<sup>-3</sup> for density and 0.001003 kg m s<sup>-1</sup> for viscosity. The model assumptions for the designated inlet and outlet are given in Table 2.

All simulations were performed on a core (TM) i7-6700K CPU at 4.00 GHz with 32.0 GB RAM.

### 2.2.3. Mesh Independency and Model Validation

The geometry of the model was meshed by a hybrid of tetrahedral and hexagonal elements as shown in Table 3a. A structural mesh has many advantages such as reducing the grids and consequently the simulation run time, but it was difficult to confirm as a single block for this case. Matching and merging the separated meshed volume was a big challenge. If the annulus was assumed symmetric, the structural mesh was perfect. While, due to the complexities in the geometry, it was not possible to mesh it structurally. There were nozzles, cutting inlet and drilling fluid outlet and they made the geometry of the model hard to mesh. Likewise, in this study, there were three main sections and in each of them the turbulent flow regime, fluctuation in the flow parameters and the velocity of the drilling fluid were different especially in the inlet section (cutting inlet and nozzles) there were five velocities inlet surfaces. Unstructured mesh was a better choice due to these constraints and limitations. Each inlet and outlet section had the separated subsections. The mesh generation for each section led to specific errors in Fluent software. With changing the mesh type from structured to unstructured, the ANSYS Fluent errors were resolved within the volume

**Table 1** The cutting properties in CFD model based on the Kinetic Theory for Granular Flows (KTGF) .

Variables	Assumptions	References	Reasons
Type	Carbonate with 100 kg kmol <sup>-1</sup> molecular weight	[19]	CFD modelling of cutting transport based on the experimental data for detecting the critical inclination window in slant wells
Density/kg m <sup>-3</sup>	2800		
Mean diameter/m	0.0009		
Granular temperature/m <sup>2</sup> s <sup>-2</sup>	Algebraic based on phase property		
Frictional pressure/Pa	Based on KTGF		
Frictional viscosity/Pa.s	Schaeffer		
Bulk viscosity/Pa.s	Lun <i>et al.</i>		
Angle of internal friction/degree	30		
Lift coefficient	Saffman-mei		
Turbulent dispersion force/N	Lopez-de Bertodano		
Granular viscosity/kg m-s <sup>-1</sup>	Gidaspow	[7]	A verified liquid–solid CFD model based on the KTGF
Solid pressure/Pascal	Lun <i>et al.</i>	[26]	A vertical liquid–solid fluidized bed that had an initial mass
Radial distribution/m	Lun <i>et al.</i>		
Packing limit	0.63	[27]	A liquid–solid fluidized bed
Drag coefficient	Schiller-Neumann	[28]	Hydrodynamic study of a multiphase spouted column
Restitution coefficient	0.9	[29]	CFD simulation of dynamic characteristics in liquid–solid fluidized beds

**Table 2** The designated inlet and outlet assumptions in the model.

The cutting inlet	A mass flow inlet for water as the formation fluid entrance with 0.333 g s <sup>-1</sup>	[19]	Based on the experimental data
The nozzles	Velocity inlet with 5.4 m s <sup>-1</sup> velocity magnitude that was normal to boundary.		
The cutting outlet	Pressure outlet	[30]	CFD modelling of the effect of drill pipe rotation on the cutting transport

interfaces. The unstructured mesh was more flexible than the structured mesh type.

In this study, three types of mesh with different mesh numbers were applied. The mesh properties such as maximum ortho-skew, minimum orthogonal quality, the existence of boundary layer and aspect ratio were shown in Table 3b. For the investigation of mesh independency, the results of the three mesh types were compared to each other in the ANSYS Fluent software environment (Table 3c). The results of cutting transport experiments were compared to the simulation results. For the validation of the simulation results, the calculated error value between the experience and simulation results was used (Table 3d).

#### 2.2.4. CFD Tests

The effect of the main drilling characteristics such as inclination, drill pipe rotation, cutting size, nozzle velocity, drilling fluid and the jetting angle on the hole-cleaning phenomena were investigated with CFD simulations. Table 4 summarizes the design of experiment parameters including the test ID and the testing parameters. The effect of inclination was studied from test T1 to T7. The effects of cutting size (from T8 to T10), drill pipe rotary speed (from T11 to T13), nozzle velocity (from T14 to T16), the combination of the effective characteristics (from T18 to T19) and the jetting angle (from T20 to T22) were investigated under three configurations.

Table 5 lists the parameters of four experiments designed to

evaluate the effect of the nozzle jetting angle (test numbers: T1, T5, T21 and T22).

Each test has a specific label. Table 6 gives the details of a typical sample label of 'T1V15S1RPM110WINC90'.

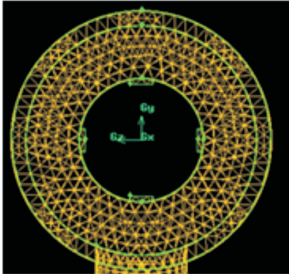
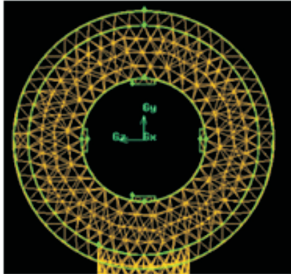
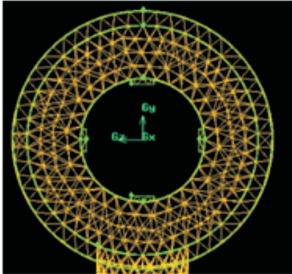
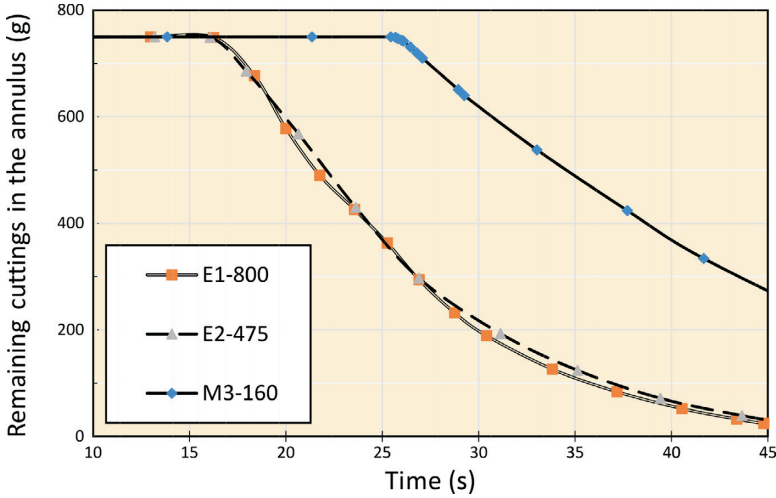
### 3. Results and Discussion

A decline in the nozzle velocity or annular velocity can lead to an increase in the cutting amount. In addition, there is a correlation between the increasing amount of the cuttings and the increasing of the rate of penetration (ROP). In this situation the amount of cuttings, the bed length and the height are increased and also the hole-cleaning problems such as sticking are increased. In the lower rate of penetrations, as the drill pipe rotation speed increases, the ROP increases linearly with the higher penetration rate. With the further increase the ROP rate decreases and it leads to the low hole-cleaning efficiency. Note that removing the drill pipe rotation has no effect on the hole cleaning of the slant wells at the high velocities. The hole cleaning of horizontal sections is one of the hard situations in the cutting transport. As mentioned in the introduction, drill pipe rotation speed, drilling fluid rheological properties, the flow rate or nozzle velocity and the time are the most important characteristic ones.

The main characteristics considered in this study are: inclination, rotary speed, fluid viscosity, cutting size, nozzle velocity and jetting angle.



**Table 3** Cross-section view of the meshes. (a) The properties of the meshes. (b) Mesh independency was met by bringing the results of the three main meshes into comparison (c). The verification of the model is shown by comparing the experiment data and model prediction values of the simulations (d).

(a)																																															
Mesh name	E1-800	E2-475	M3-160																																												
Cross-section view:																																															
(b)																																															
Properties	E1	E2	M3																																												
Aspect ratio	15/99	15/24	25/95																																												
Max ortho skew	0/755	0/710	0/832																																												
Min orthogonal quality	0/18	0/250	0/640																																												
Boundary layer	Yes	Yes	No																																												
Mesh grid number	800,000	475,000	160,000																																												
(c)																																															
																																															
(d)																																															
<table><tr><th colspan="2">Experiment</th><th colspan="2">E2-475</th></tr><tr><th>Time/s</th><th>Remaining cuttings in annulus</th><th>Predicted mass</th><th>Error /%</th></tr><tr><td>0</td><td>750</td><td>750</td><td>0.0</td></tr><tr><td>5</td><td>750</td><td>750</td><td>0.0</td></tr><tr><td>10</td><td>750</td><td>750</td><td>0.0</td></tr><tr><td>15</td><td>740</td><td>748</td><td>1.1</td></tr><tr><td>20</td><td>580</td><td>568</td><td>-2.1</td></tr><tr><td>25</td><td>410</td><td>400</td><td>-2.4</td></tr><tr><td>30</td><td>260</td><td>250</td><td>-3.8</td></tr><tr><td>35</td><td>120</td><td>115</td><td>-4.2</td></tr><tr><td>40</td><td>80</td><td>75</td><td>-6.3</td></tr></table>				Experiment		E2-475		Time/s	Remaining cuttings in annulus	Predicted mass	Error /%	0	750	750	0.0	5	750	750	0.0	10	750	750	0.0	15	740	748	1.1	20	580	568	-2.1	25	410	400	-2.4	30	260	250	-3.8	35	120	115	-4.2	40	80	75	-6.3
Experiment		E2-475																																													
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0	750	750	0.0																																												
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40	80	75	-6.3																																												

**Table 4** Experiment parameters in different configurations.

Test no.	Test name	Main parameter	Inclination	Drill pipe rotation speed /RPM	Cutting size /mm	Nozzle velocity /m s <sup>-1</sup>	Drilling fluid
1	T1-INC 0 Case 1	Inclination	0	110	1	15	Water
2	T2-INC 90	Inclination	90	110	1	15	Water
3	T3-INC 45	Inclination	45	110	1	15	Water
4	T4-INC 15	Inclination	15	110	1	15	Water
5	T5-INC 30 Case 3	Inclination	30	110	1	15	Water
6	T6-INC 60	Inclination	60	110	1	15	Water
7	T7-INC 75	Inclination	75	110	1	15	Water
8	T11-SIZE 5	Cutting size	0	110	5	15	Water
9	T12-SIZE 5	Cutting size	90	110	5	15	Water
10	T13-SIZE 5	Cutting size	30	110	5	15	Water
11	T21-RPM 0	Drill pipe rotation (RPM)	0	0	1	15	Water
12	T22-RPM 0	Drill pipe rotation (RPM)	90	0	1	15	Water
13	T23-RPM 0	Drill pipe rotation (RPM)	30	0	1	15	Water
14	T41-NV 5	Nozzle velocity	0	110	1	5	Water
15	T42-NV 5	Nozzle velocity	90	110	1	5	Water
16	T43-NV 5	Nozzle velocity	30	110	1	5	Water
17	T52-RPM0-NV	Fluid Type-RPM	90	0	1	5	Newtonian-viscous 10 cp
18	T62-RPM110-NV	Fluid type	90	110	1	5	Newtonian-viscous 10 cp
19	T72-RPM0-W	RPM	90	0	1	5	Water
20	Case 2	Nozzle angles	0	110	1	15	Water 30-45-60-75 arrangement
21	Case 4	Nozzle angles	30	110	1	15	Water 45-45-45 arrangement

**Table 5** Tests parameters for the evaluation of the influence of nozzle angle (jetting angles) and inclination.

Test no.	Test name — Different model type	Inclination (degree)	Nozzle angles (degree)			
			N#1	N#2	N#3	N#4
1	Case 1	0	90	90	90	90
22	Case 2	0	75	60	45	30
5	Case3	30	90	90	90	90
21	Case 4	30	45	45	45	45

### 3.1. Inclination

Directional wells can be categorized into four types, namely S-shaped, slanted, inclined and horizontal types. In each type, if the pump is turned off, the cuttings are slumped in the low side of the borehole bottom due to gravity. The minimum amount of hole cleaning occurs in a critical inclination, at which the cutting transport is more problematic.

In CFD simulation, the critical inclination can be determined with different approaches. In the first method, the volume fraction was calculated at different times. In the second approach, the sand and water velocities are compared across the annulus at

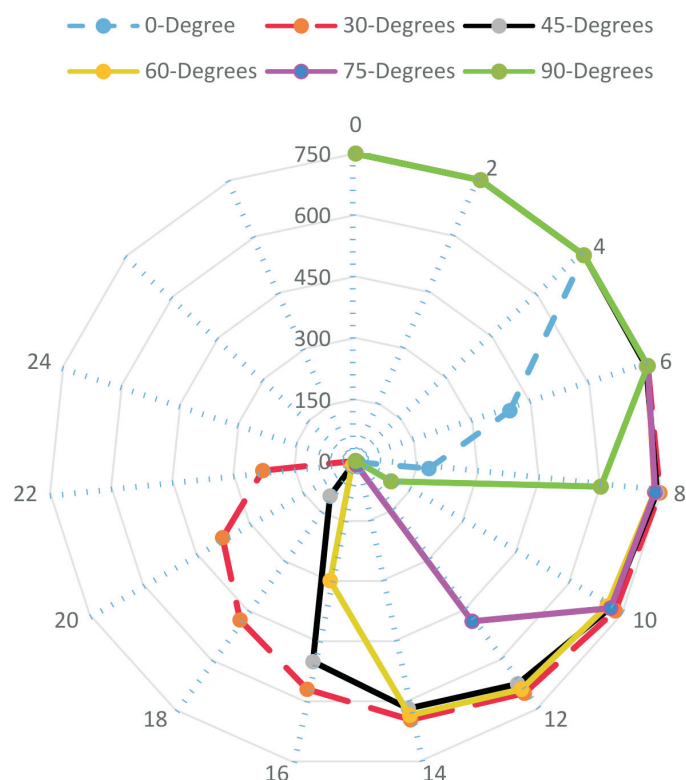
different times. Lastly, the critical inclination was determined based on the knowledge of the mass of the remaining cuttings in the annulus. It was found that the remaining cuttings in the annulus were increased by increasing the inclination from 0 to 30 degrees and then it was decreased from 30 to 75 degrees inclination (Fig. 2). In all approaches, it was found that the critical inclination angle was approximately 30 degrees.

### 3.2. Drill Pipe Rotary Speed and Drilling Fluid Viscosity

The agitation and rotation of drill string improve the cutting transport process by decreasing the pressure drop and cutting bed height across the annulus. The rotation of drill string has no significant effect on the cutting transport process at high flow rates. In other words, the effect of the drill string rotation in assisting cutting transport can be replaced by increasing the flow rate. At high flow rates, during the drilling operation, the rotation of drilling string did not affect the cutting transport a lot. In the presence of water or Newtonian viscous fluids as drilling fluids, at low flow rates but at high speeds of drilling rotation, the initial hole-cleaning time was not affected by these parameters. However, in the state of the drilling string with no rotation, the time for completing the hole cleaning changed for each drilling

**Table 6** Description of a sample test name.

Label sample	Range	Description
T1-V15-S1-RPM110-W-INC90	T1 to T72	Test name
T1-V15-S1-RPM110-W-INC90	V5 & V15	Velocity range
T1-V15-S1-RPM110-W-INC90	S1 & S5	Cutting size range
T1-V15-S1-RPM110-W-INC90	RPM0 & RPM110	Rotary speed range
T1-V15-S1-RPM110-W-INC90	W & NM	Water or Newtonian mud
T1-V15-S1-RPM110-W-INC90	INC0 to INC90	Inclination

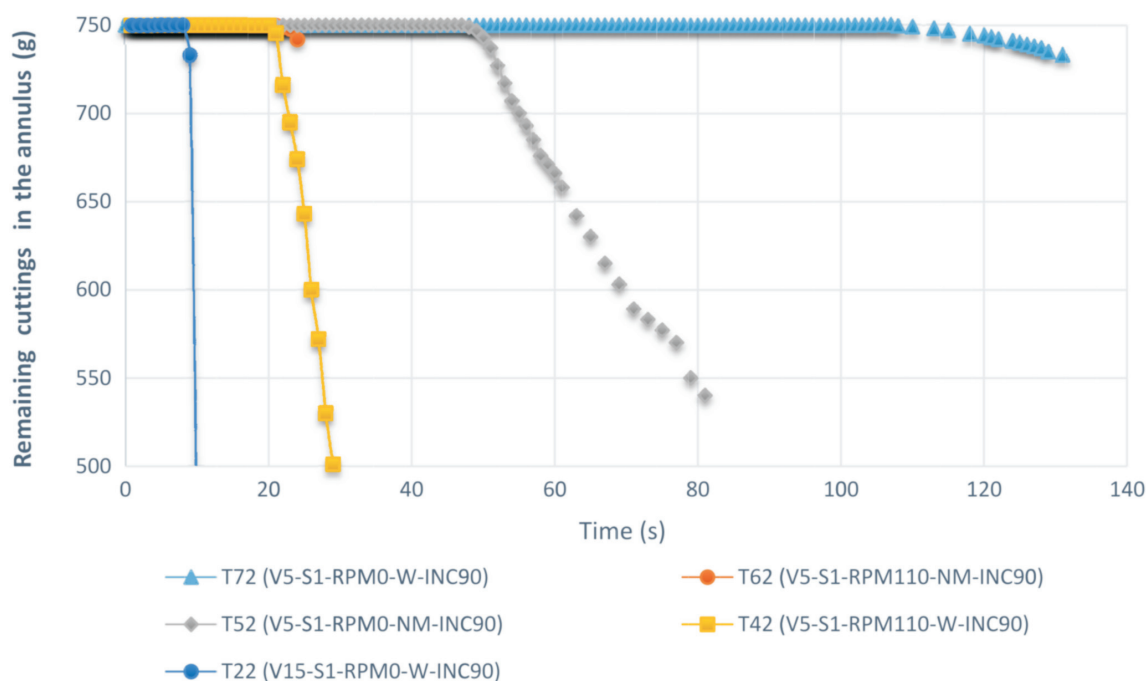


**Figure 2** Effect of inclination on the hole-cleaning time. The initial mass (i.e. 750 g) removed after simulating the drilling fluid pumping. The needed time for each inclination is different. The vertical annulus (0 degree) shows the lowest cleaning time amount and 30-degree shows the highest cleaning time.

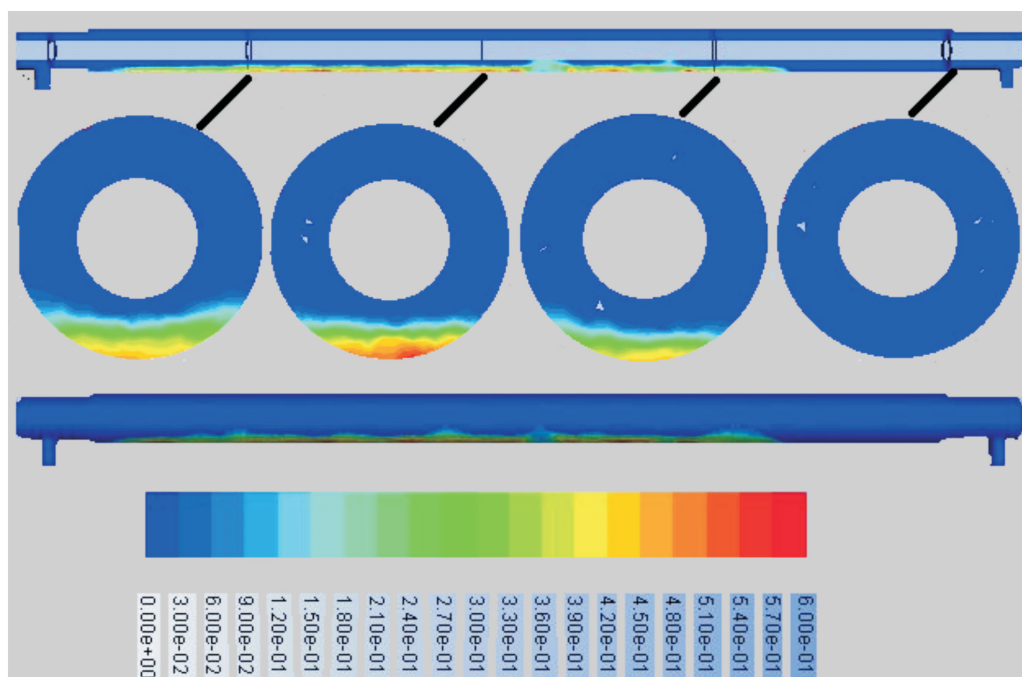
fluid. In the horizontal sections in similar operational conditions, the hole-cleaning time for water at low flow rates and non-rotating pipe (T52-RPM0-NV) was approximately two times of the hole-cleaning time for a Newtonian viscous fluid (T42-NV 5) (Fig. 3). This can be interpreted as the roles of viscous force in increasing the cutting carrying capacity.

In this study, the effect of drilling fluid viscosity was investi-

gated on cutting transport by water with 1 cp and a high viscosity Newtonian fluid with 10 cp of viscosity. Using viscous fluid forms a specific cuttings transport regime across the annulus. Figures 4 and 5 show the effects of viscous drilling fluid in the presence of the drilling string rotation and no rotation of the drilling string in a horizontal section. Figure 4 is a snapshot of the system with no rotation of the drilling string after 30 seconds in



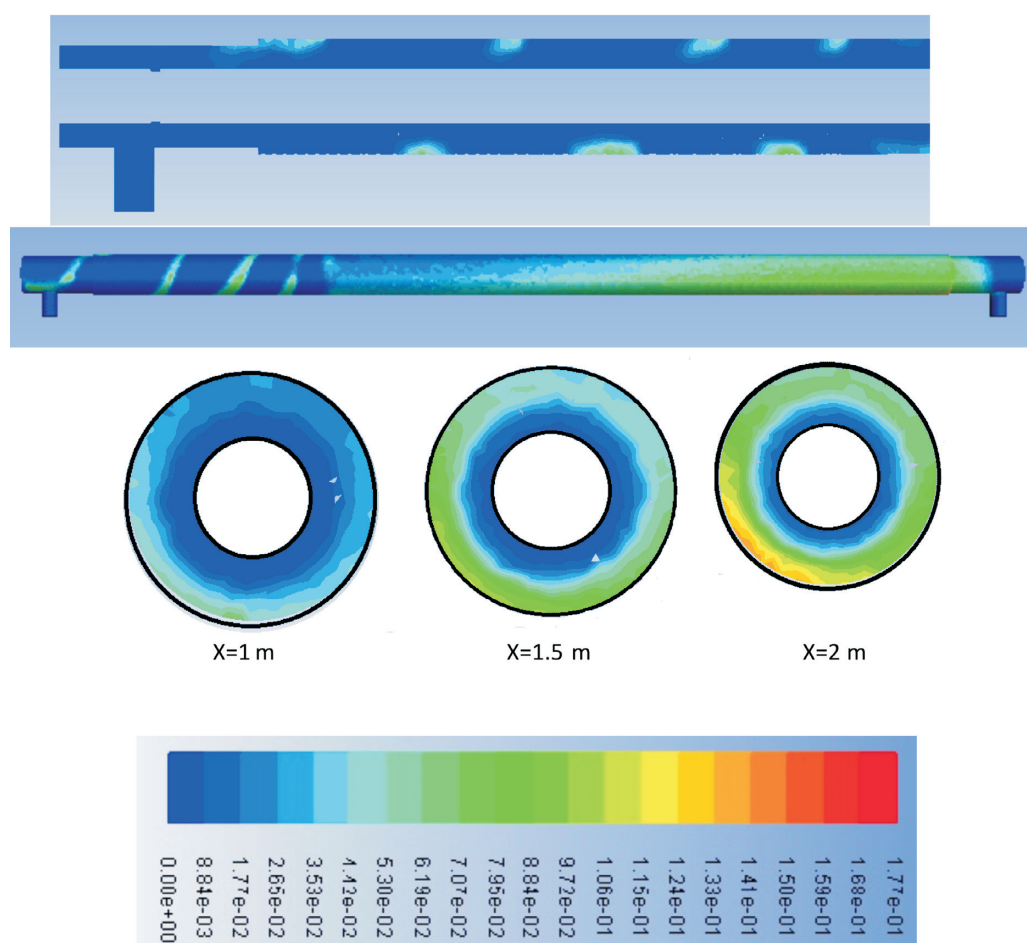
**Figure 3** Effect of viscosity and the drill pipe rotation speed on different flow rates and times on the remaining cuttings in the horizontal annulus. The worst one (130 s) in time duration corresponds to the T72 and the best one (10 s) in time duration is T22. The complete information is given in Table 4.



**Figure 4** Effect of Newtonian viscous fluid (10 cp) on the sand volume fraction in the non-rotating drill pipe in the horizontal annulus after 30 seconds.

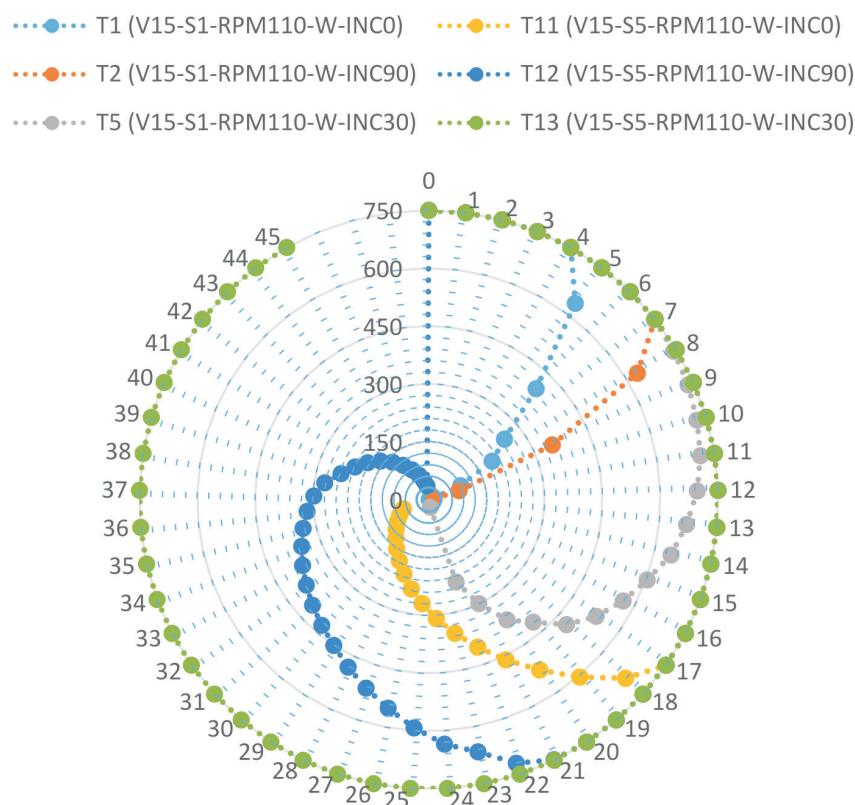
different cross-sections. In this state, the cutting bed extended on the low side of the system as the cross-section views show. As the cutting bed has been moved and extended from the first points of the system, its height was increased gradually toward the middle points of the system. Hence, at the end points of the

system, the height of the cutting bed was decreased. This state can demonstrate the effect of viscosity in increasing the shearing forces to pick up and carry the cutting from the cutting bed into the drilling fluid. This caused the cutting bed to gradually creep toward the outlet.



**Figure 5** Effect of Newtonian viscous fluid on the sand volume fraction in the rotating drill pipe rotation in a horizontal annulus after 23 seconds.





**Figure 6** Effect of cutting size on the hole-cleaning time at different sections, showing that there is no outlet in T13 and the lowest removing time corresponds to T1. The complete information is given in Table 4.

In the state of the drilling string rotating, as is obvious in Fig. 5 after 23 seconds, the cuttings were dispersed in the annulus and there was no concern for forming the cutting bed in the horizontal section. The cuttings were agitated by the rotation of the drilling string and moved spirally toward the outlet. As shown in the cross-section views in Fig. 5, the cuttings were agitated and rotated around the drilling string and they were picked up from the low side to the annulus space and carried by the flow regime.

### 3.3. Effect of Cutting Size

To investigate the effect of particle size on the cutting transport; two particle sizes (1 mm and 5 mm) were selected. These sizes are normal cutting sizes in drilling operations. Figure 6 shows the results of 1 and 5 mm of particle sizes on the hole-cleaning time. The hole-cleaning time was prolonged as the cutting size increased. In the critical inclination, increasing the particle size had an adverse effect on the hole-cleaning process and almost no cuttings were carried out of the annulus (T13). However, in vertical (T11) and horizontal (T12) conditions, an increase in the particle size results in much more time for an efficient hole cleaning.

### 3.4. Effect of Nozzle Velocity

In this section, the effects of the nozzle velocity on the cutting transport were investigated for two jetting velocities ( $5 \text{ m s}^{-1}$  and  $15 \text{ m s}^{-1}$ ). For  $15 \text{ m s}^{-1}$  velocity of the nozzle jetting, the cleaning process of the annulus was efficient at all inclinations, whereas, for  $5 \text{ m s}^{-1}$  of jetting velocity of nozzles, the cleaning process took longer for both vertical and horizontal sections. CFD results demonstrated that in the critical inclination, no cutting was carried to the outlet by decreasing the nozzle velocity from  $15 \text{ m s}^{-1}$  to  $5 \text{ m s}^{-1}$  (see Fig. 7).

Figure 8 shows a streamline contour view of the system after

2.065 seconds from the drilling fluid pumping. The streamlines were started from the nozzle and flown through the system.

### 3.5. Jetting Angle

In this section, the effects of jetting angle on the hole cleaning were studied for three different patterns of nozzle angles (Fig. 9) due to different types of nozzle arrangement in common bit types (Fig. 10). Initially, a mixed pattern of 75, 60, 45, 30 nozzle angles was used for a vertical annulus and after that due to the poor hole cleaning at the low nozzle velocity ( $5 \text{ m s}^{-1}$ ) at 30-degrees of inclination, we investigated the effect of changing the nozzle angles to 45-degree rather than the normal vector of the jetting surface.

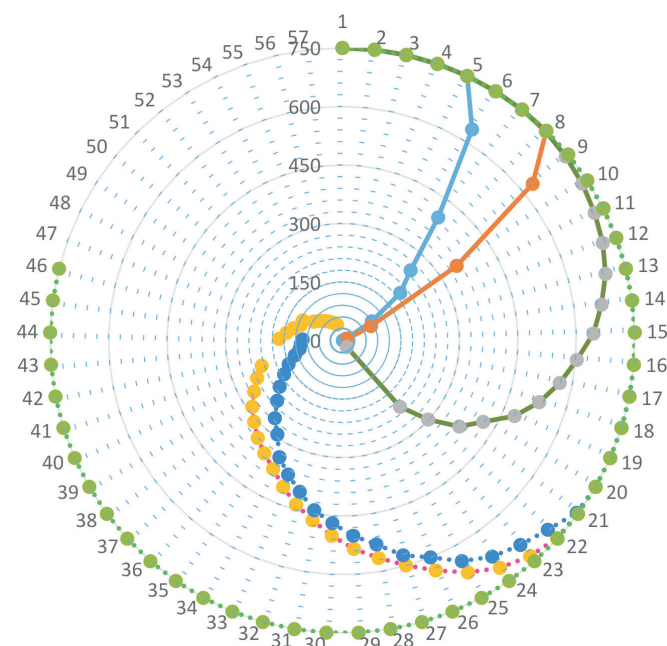
#### 3.5.1. INC30-90 Degree Nozzle Angle

In this case, the cutting transport process was investigated by the system in 30 degrees inclination with 90 degrees nozzle angles. The cuttings were deposited on the low side of the annulus. A narrow tail of the cuttings was formed on the low side and traced toward the output of the annulus. The cuttings were carried to the upper part of the annulus space, but according to this inclination as the critical inclination (30 degrees), the cuttings slumped down on the low side of the annulus space. Eventually, they were deposited over each other, massively on the lower side of the annulus (Fig. 11).

In this situation, after 40 seconds about less than 1 gram of cuttings had exited from the annulus space which is very small compared to the elapsed time of the drilling fluid pumping.

#### 3.5.2. Mixed Pattern (75, 60, 45, 30 Degrees)

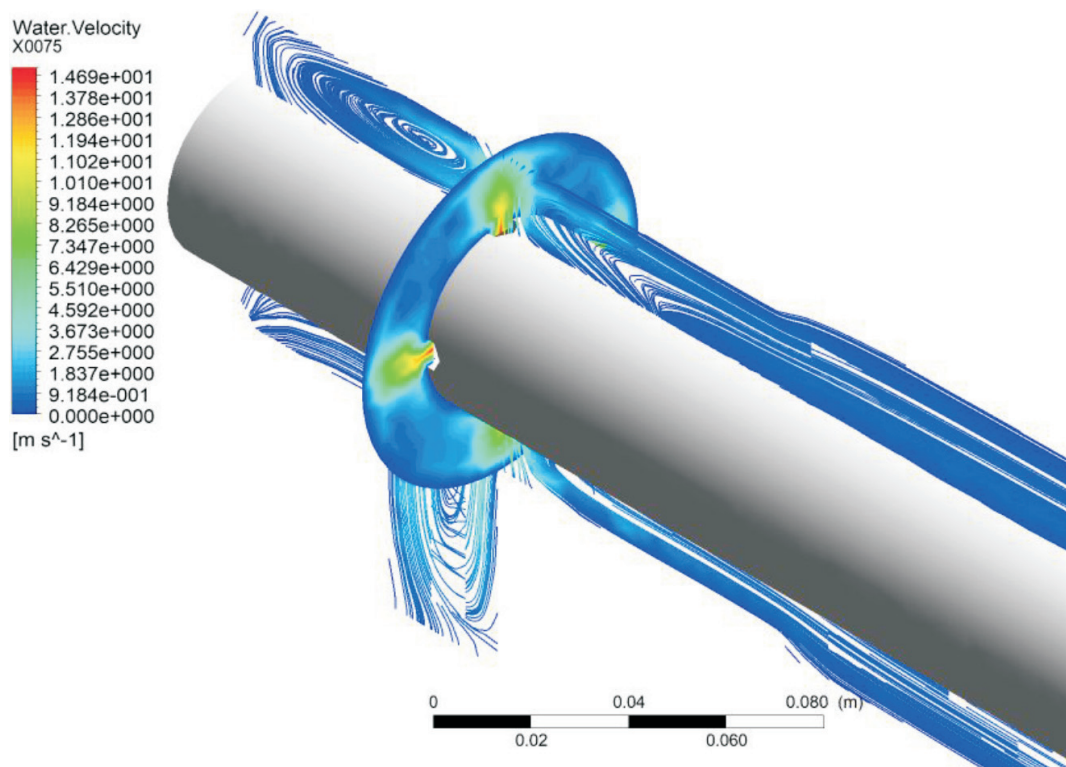
In this case, a mixed pattern of nozzle jetting angles was studied. 750 grams of the cuttings was injected into the annulus space after that the drilling fluid (water) was pumped after 500 seconds all of the cuttings were evacuated from the annulus



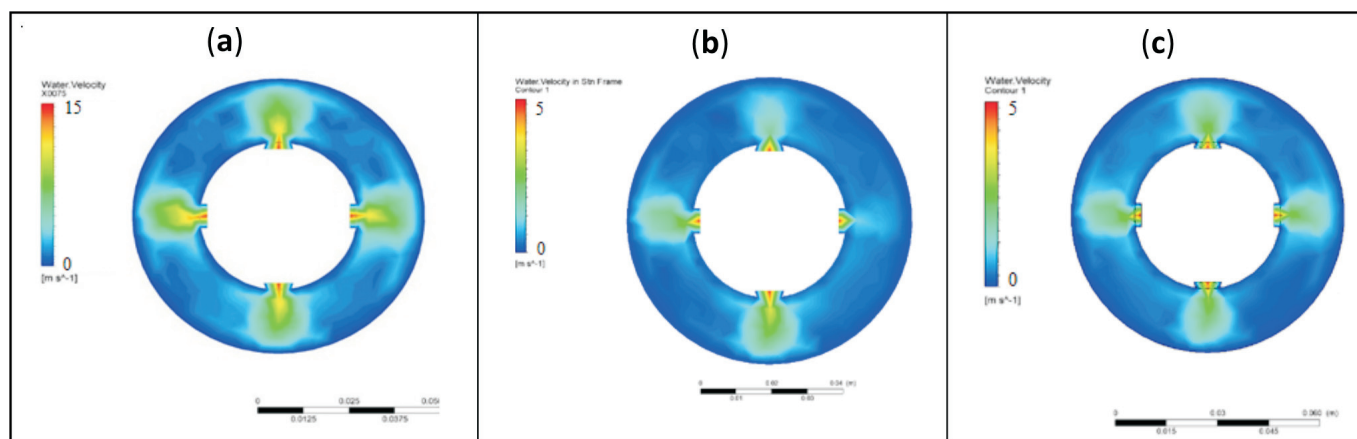
**Figure 7** Effect of the nozzle velocity at different sections on the hole-cleaning time showing there is no cutting in the outlet in T43 and the lowest removing time corresponds to T1 sample. Complete information is given in Table 4.

space. After 70 seconds of pumping water, the cuttings were dispersed in the annulus space, but some separated bulks of the cuttings were formed around the drilling string. It can be illustrated that the rotation of the drilling string agitated the whole mass of the cuttings and cut them into smaller bulks that can be carried by drilling fluid. This simulation demonstrated that the

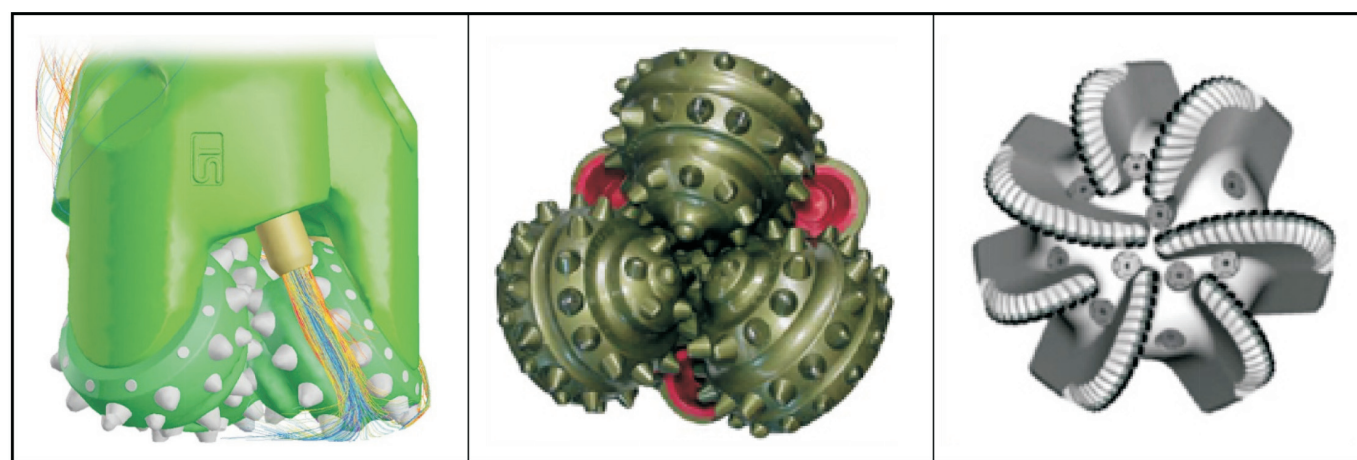
mixed pattern of nozzle angles was not as effective as the 90-degree nozzle angle pattern on the cutting transport process. Even after about 500 seconds of the simulation, there was still about 50 grams of the cuttings in the annulus space. Changing the nozzle angle into the mixed pattern resulted in an improper hole cleaning and the hole-cleaning time was sharply increased.



**Figure 8** Water velocity streamlines with contour view on nozzles YZ plane show the streamlines are started from nozzles and cutting inlet section (2.056 s after starting to pump).



**Figure 9** (a) 90 degree jetting angles of the nozzle (perpendicular to the drill pipe) with  $15 \text{ m s}^{-1}$  velocity in 30-degrees inclination. (b) A mixed pattern of the jetting angles of the nozzle with  $5 \text{ m s}^{-1}$  velocity in a vertical annulus. (c) The 45-degree jetting angles of the nozzle with  $5 \text{ m s}^{-1}$  velocity in 30-degrees inclination



**Figure 10** Nozzle placement and the nozzle angles in different common bit types.

In practice, the nozzle angle design has a strong effect on the near bit cleaning as the first point of hole-cleaning process. Improper design of the nozzle angles can cause poor near bit cleaning, bit ball, bit burning and consequently increasing drilling time and cost.

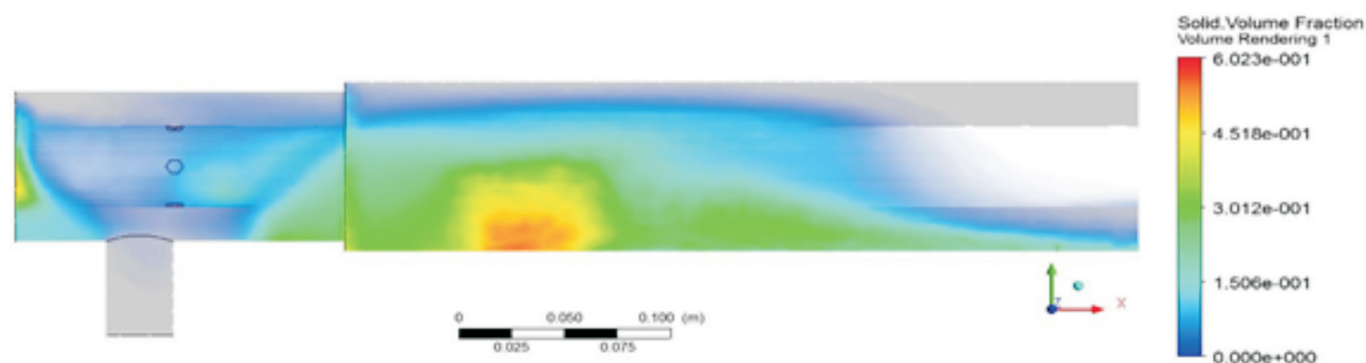
In this case, as Fig. 12 shows after about 500 seconds almost 750 g of cuttings were evacuated from the annulus space.

### 3.5.3. INC30 – Nozzle Angle 45 Degrees

In this simulation, the nozzle angles were changed to 45-degrees (Fig. 9). For 30-degree inclination as the critical inclination, in practice, almost no cutting was transported out of the

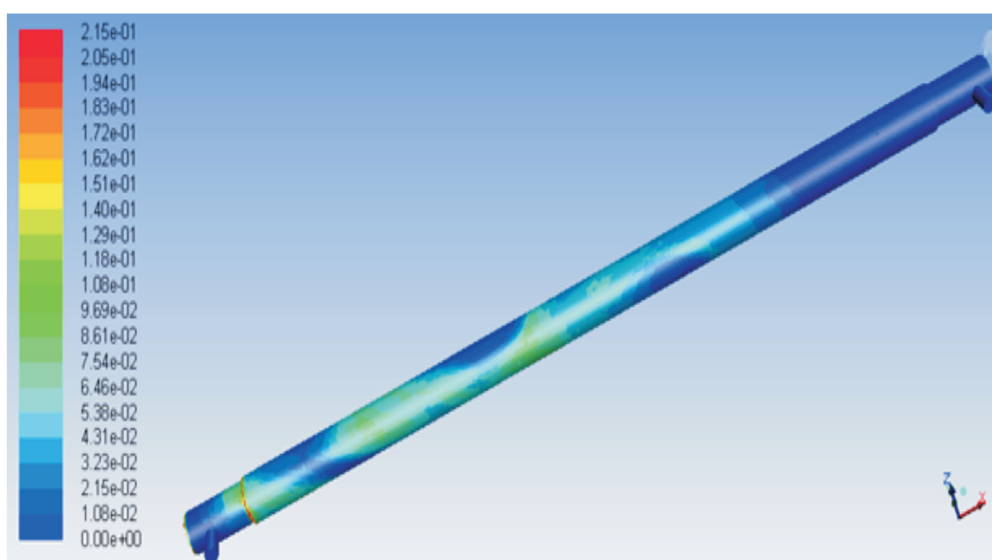
annulus (less than 1 g). This amount of cuttings was very negligible rather than the elapsed time of the simulation (Fig. 13).

Similar to the previous case, the cuttings were deposited on the low side of the annulus over each other and due to the rotation of the drill string, a snake tail of cuttings was extended on the low side of the annulus space toward the output. The tail was not as thick as the pattern with 90 degrees jetting angles. Similarly, due to the previous case, the cuttings were carried up by the flow regime to the upper parts of the annulus; however, they were slumped down and deposited at the bottom of the annulus. Maybe an increase in the flow rate can carry the cuttings out of the annulus space.

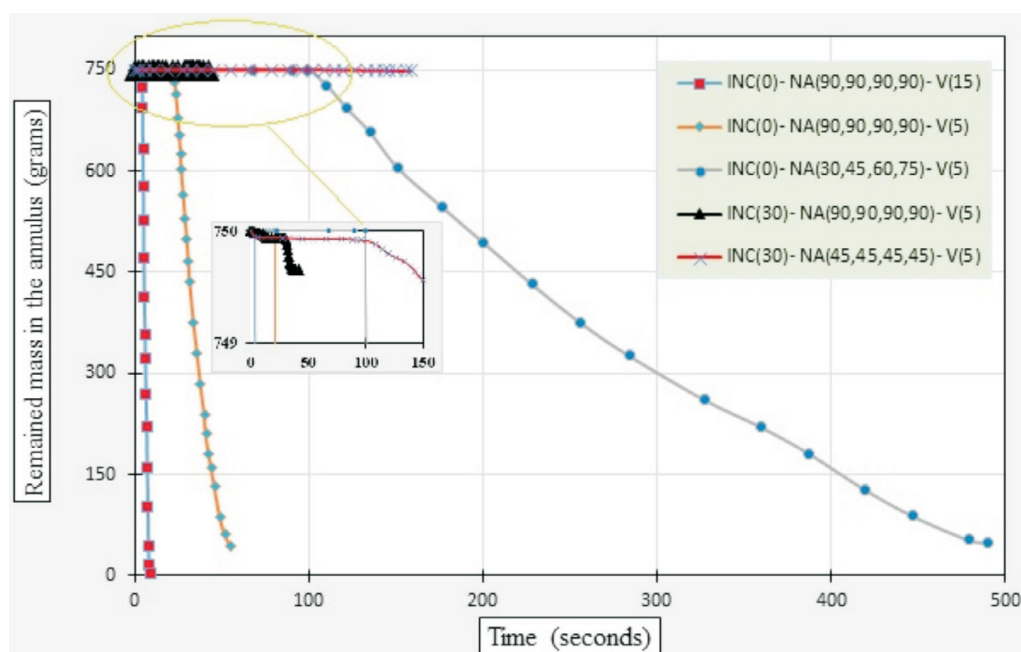


**Figure 11** Contour plot of annulus system created by CFD post at 30-degree inclination system and 90-degree nozzle angles after 41.78 seconds.





**Figure 12** Contour plot of annulus system for vertical system and 75, 60, 45, 30-degree nozzle angles (mixed angle pattern) after 70.2 seconds of starting drilling fluid pumping in vertical section.



**Figure 13** The effect of nozzle arrangement angle at different inclinations (0 and 30 degrees) and various velocities (15 and 5 m s<sup>-1</sup>) on the remaining mass over time.

In these two cases, the nozzle angle pattern affected the bottom hole cleaning in a deviated drilling system. If two systems are considered for a certain elapsed time of 40 seconds, almost no cuttings have been exited from the system in 45-degree nozzle angles; however, when the nozzle angle pattern was 90 degrees, it was slightly more effective than the case of 45-degree nozzle angles. The 90-degree nozzle pattern generally had a better performance than the 45-degree nozzle angle pattern. It can be demonstrated that the nozzle angle pattern did not influence the cutting transport near the bit and the system inclination was a dominant factor in this situation (Fig. 13).

#### 4. Conclusion

In this study, the cutting removal was studied by using a three-dimensional model based on the kinetic theory for the granular flows. The model was further validated with the experimental data. In both experimental and CFD ANSYS

modelling, an attempt was made to remove the initial sand by the means of the water jetting.

The following are the main conclusions:

1. At low flow rates but at high speeds of the drilling string rotation, for Newtonian viscous fluids or water, the viscosity had no effect on the initial hole-cleaning times; however, by setting the speed to zero, the required time for each fluid changed.
2. As the particle size of the cuttings increased, the time of the hole cleaning increases. In the critical inclination, increasing the size had an adverse impact on the hole-cleaning progress and in practice no cuttings exited from the annulus space. However, for vertical and horizontal cases, by increasing the cutting size, the time of the hole cleaning increased.
3. In the critical inclined section, the cutting transport was stopped by lowering the nozzle velocity from 15 m s<sup>-1</sup> to 5 m s<sup>-1</sup>. The 90-degree nozzle pattern generally had the better

performance than the 45-degree arrangement. Downward jetting angle pattern was not suitable for the hole-cleaning process.

4. Adding viscosifiers into the low viscous dense fluids can lead to an increase in bed length that reduces the mechanical sticking probability.
5. All conditions that lead to a decrease in cutting size can be efficient for the cutting transport process.
6. The 90-degree nozzle pattern generally has better performance than the 45-degree arrangement at the critical inclination.
7. In the critical inclination, downward jetting angle pattern is not profitable for the hole-cleaning process.

### Nomenclature

$C_d$	Drag coefficient
$d$	Diameter (m)
$e$	Restitution coefficient
$g$	Gravity ( $\text{m s}^{-2}$ )
$g_o$	Radial distribution function
$k_\Theta$	Diffusion coefficient for granular energy ( $\text{kg ms}^{-1}$ ) Unit tensor
$I_{2D}$	Second invariant of deviatoric stress tensor
$p$	Pressure (Pa)
$\mathbf{v}$	Velocity vector ( $\text{m s}^{-1}$ )
$Re$	Reynolds number
$t$	Time (s)
$x$	Particle concentration
$M_0$	Initial patched mass (gram)
$M_t (M_{in})$	Current mass in the annulus (gram)
$M_{out}$	Exited mass from the annulus (gram)
$t_{1/2}$	The time of exiting semi amount of initial patched mass

### Greek letters

$\alpha$	Volume fraction
$\rho$	Density ( $\text{kg m}^{-3}$ )
$\tau$	Stress tensor (Pa)
$\beta$	Inter-phase momentum exchange coefficient ( $\text{kg m}^3 \text{s}^{-1}$ )
$\gamma$	Collisional energy dissipation ( $\text{kg ms}^{-3}$ )
$\lambda$	Bulk viscosity ( $\text{kg ms}^{-1}$ )
$\mu$	Shear viscosity ( $\text{kg ms}^{-1}$ )
$\alpha_{s,max}$	Maximum solid volume fraction
$\Theta$	Granular temperature ( $\text{m}^2 \text{s}^{-2}$ )
$\emptyset$	Internal friction angle ( $^\circ$ )

### Subscripts

$l$	Liquid phase
$s$	Solid phase

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