

Numerical Investigation of Pressure Recovery for an Induced Draught Fan Arrangement

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Abstract: This study investigates the potential gain in operating volume flow rate and static efficiency for an induced draught fan arrangement by reducing the outlet kinetic energy loss. The reduction is achieved through pressure recovery, which is the conversion of dynamic pressure into static pressure. Downstream diffusers, stator blade rows, or a combination of these can recover pressure. Six different discharge configurations are tested for a fan. An annular diffuser with equiangular walls at an angle of 22° from the axial direction and a length equal to the fan diameter recovers the most pressure over a range of volume flow rates. The diffuser causes the operating volume flow rate and static efficiency to increase by 6.3 % (relative) and 20 % (absolute), respectively, compared to the initial design point of the particular fan.

Additional keywords: Pressure recovery, induced draught, diffuser, stator, axial flow fan.

Nomenclature

Roman

A	Area [m ²]
AR	Diffuser area ratio
a	Curve fitting coefficient
f	Elliptic damping function [1/s]
C_μ	Closure coefficient
K	Pressure loss or gain coefficient
k	Turbulence kinetic energy [m ² /s ²]
l	Length [m]
l_t	Turbulence length scale [m]
P_F	Fan power consumption [W]
Δp	Pressure differential [Pa]
r	Radius [m]
U, V, W	Mean velocities along, normal, and tangential to wall [m/s]
U_0	Mean inlet velocity [m/s]
\dot{V}	Volume flow rate [m ³ /s]
v	Velocity [m/s]

$\overline{v'^2}$	Turbulence stress normal to streamlines [m ² /s ²]
x, y, z	Directions along, normal, and tangential to a wall
y	Normal distance from wall [m]
y^+	Sublayer-scaled normal distance from wall

Greek

α_e	Kinetic energy correction factor
β^*	Closure coefficient
ε	Turbulence dissipation rate [m ² /s ³]
η	Efficiency [%]
θ	Diffuser half-wall angle [deg]
μ	Molecular viscosity [kg/(m s)]
μ_t	Eddy viscosity [kg/(m s)]
ν	Kinematic molecular viscosity [m ² /s]
ρ	Air density [kg/m ³]
ω	Turbulence specific dissipation rate [1/s]

Subscripts

c	Cross-section
des	Design point
dif	Diffuser
$dump$	Dump to represent the open atmosphere
F	Fan
FC	Fan casing
F/dif	Fan-diffuser unit
i	Inner wall
$inlet$	Inlet boundary
max	Maximum
o	Outer wall
op	Operating point
rec	Recovery of dynamic to static pressure
s	Static
sys	System
t	Total
z, θ, r	Cylindrical coordinate directions
∞	Atmospheric conditions at outlet boundary

Abbreviations

ACC	Air-cooled condenser
ADM	Actuator disc model
CFD	Computational fluid dynamics
CSP	Concentrated solar power
EADM	Extended actuator disc model
GAMG	Geometric-algebraic multi-grid
PBiCG	Preconditioned bi-conjugate gradient
RNG	Renormalized group
RSM	Reynolds-stress model
SIMPLE	Semi-implicit method for pressure-linked equations
SST	Shear-stress transport

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1 Introduction

Power plants, such as concentrated solar power (CSP) plants, are often located in arid areas where the availability of water for wet-cooling is limited. Kröger [1] predicted that diminishing cooling water supplies coupled with increased water costs and environmental considerations would result in increased reliance on ambient air for cooling purposes.

Mechanical draught air-cooled condensers (ACCs) employ air as the cooling medium. Moore *et al.* [2] estimate that ACCs can potentially reduce the water consumption of a power plant by as much as 90 %. Therefore, ACCs are often the only feasible option for CSP applications.

Owing to the relatively low pressure rise and high volume flow rate required by a typical ACC, they typically employ a large array of axial flow fans to force or induce the airflow through the heat exchangers. In an induced draught ACC, the fans are located downstream of the heat exchanger bundles. The kinetic energy in the air exiting the fans that discharges into the atmosphere is a loss to the fan system. This study aims to investigate configurations for reducing the outlet kinetic energy loss of an induced draught fan arrangement. This will be achieved by converting a portion of the dynamic pressure loss at the fan outlet into static pressure—a process termed pressure recovery.

Pressure recovery can be achieved with a discharge diffuser, stator blade row, or both. According to Walter *et al.* [3], a stator blade row will reduce the circumferential component of the dynamic pressure. Wallis [4] states that a diffuser will, as a result of the increase in radial dimension, reduce both the axial and circumferential components due to the conservation of mass and angular momentum, respectively.

The fan under consideration in this study is the M-fan of Wilkinson *et al.* [5]. They evaluated the fan numerically using a three-dimensional periodic fan model with a zero tip clearance. The design specifications and performance characteristics of the fan at the design flow rate are listed in table 1.

Table 1: M-fan specifications and performance characteristics at the design flow rate.

Specification	Value
Diameter	24 ft (7.3152 m)
Number of blades	8
Hub-to-tip ratio	0.29
Blade root setting angle	34°
Rotational speed	151 rpm
Design flow rate	333 m ³ /s
Fan static pressure rise	114.7 Pa
Fan power consumption	64.24 kW
Fan static efficiency	59.4 %

Full-scale testing on ACC fans is often impractical due to their large physical size. The number of discharge configurations to test for the M-fan is also too extensive for scaled-down experiments. Computational fluid dynamics (CFD) was therefore used for the current investigation.

Prior to performing the simulations using the M-fan data, the CFD was validated against the experimental data of Clausen *et al.* [6] for swirling flow in a conical diffuser. The

modelling strategies that provided the best results were then applied to the M-fan simulations.

Modelling the full-scale M-fan in detail would require enormous computational resources. The same holds for the blade passages of a downstream stator. Since the current study is only interested in the flow downstream of the M-fan, fixed outlet velocity profiles for the M-fan were used as inlet conditions for the computational domain. The fan was therefore not modelled. To simulate the effect of stator blades on the air stream, the extended actuator disc model (EADM) of Van der Spuy [7] was adopted. This model does not require detailed modelling of the blade passages and allows for a steady-state treatment of the flow through the stator. These simplifications substantially reduced the computational complexity of the flow problem.

The paper starts by demonstrating how pressure recovery affects the characteristics of an induced draught fan arrangement. Details of the numerical strategies and validation study follow. The pressure recoveries obtained with six different discharge configurations for the M-fan are then presented. Thereafter, the results of the configuration that had the highest pressure recovery were added to the M-fan characteristics to obtain the combined characteristics of the fan-diffuser unit. The paper ends with conclusions on the main findings.

2 Effect of Pressure Recovery on the Draught Equation of an Induced Draught ACC

The draught equation for an ACC is a mechanical energy relation that equates the mechanical energy supplied to the air by the axial flow fan to the energy dissipated through the ACC [8]. Pressure changes through the ACC are represented by a dimensionless pressure loss or gain coefficient, i.e.

$$K = \frac{\Delta p}{\rho v^2 / 2} \quad (1)$$

where Δp represents the pressure loss or rise, ρ is the air density, and v is an average velocity based on a characteristic cross-sectional area.

The draught equation for the induced draught ACC shown in figure 1 is given by

$$\Delta p_{Fs} + \alpha_{eFC} \rho v_{FC}^2 / 2 = \Delta p_{sys} + K_{dif} \rho v_{FC}^2 / 2 + \alpha_{edif} \rho v_{dif}^2 / 2 \quad (2)$$

where Δp_{Fs} denotes the fan static pressure rise, α_{eFC} the kinetic energy flux factor at the discharge plane of the fan, and $v_{FC} = \dot{V} / A_{FC}$ is the mean axial velocity through the fan casing. The sum of the total pressure losses through the ACC, excluding that of the diffuser and discharge kinetic energy loss, is represented by Δp_{sys} . The excluded losses are given by the last two terms, where K_{dif} is the total pressure loss coefficient of the diffuser and α_{edif} is the kinetic energy flux factor at the diffuser outlet. v_{dif} is the mean velocity at the diffuser outlet.

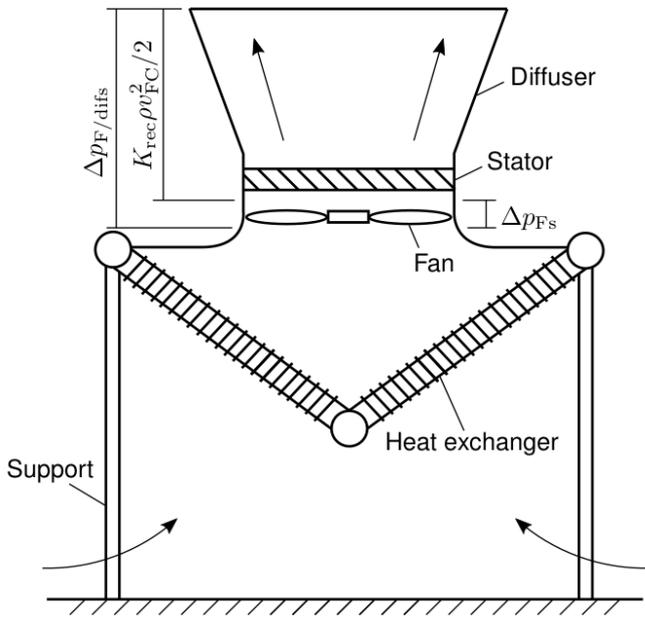


Figure 1: Schematic of an induced draught air-cooled condenser fitted with a discharge diffuser and stator. The locations of the fan static pressure, Δp_{Fs} , recovered pressure, $K_{rec}\rho v_{FC}^2/2$, and fan-diffuser unit pressure, $\Delta p_{F/difs}$, are illustrated.

Since α_{eFC} , K_{dif} and α_{edif} are generally unknown, Kröger [9] argued that it is useful to obtain the performance characteristics of the fan-diffuser unit. Four terms in equation (2) can then be replaced by

$$\Delta p_{F/difs} = \Delta p_{Fs} + \alpha_{eFC}\rho v_{FC}^2/2 - K_{dif}\rho v_{FC}^2/2 - \alpha_{edif}\rho v_{dif}^2/2 \quad (3)$$

which simplifies the draught equation to

$$\Delta p_{F/difs} = \Delta p_{sys} \quad (4)$$

In order to distinguish between Δp_{Fs} and $\Delta p_{F/difs}$, a pressure recovery coefficient, K_{rec} , is introduced. It accounts for both the kinetic energy at the fan outlet that is recovered within the discharge diffuser or stator as well as the frictional and local losses. The coefficient is defined as

$$K_{rec} = \frac{\alpha_{eFC}\rho v_{FC}^2/2 - \alpha_{edif}\rho v_{dif}^2/2 - K_{dif}\rho v_{FC}^2/2}{\rho v_{FC}^2/2} = \alpha_{eFC} - \alpha_{edif}(AR)^{-2} - K_{dif} \quad (5)$$

where $AR = A_{dif}/A_{FC}$ is the area ratio of the diffuser.

The kinetic energy flux factor is calculated by

$$\alpha_e = \frac{\rho \iint_{A_c} v_c |v|^2 dA_c}{\rho v_{FC}^2 A_c} \quad (6)$$

where v_c is the mean axial velocity through a cross-section of area A_c and $|v| = \sqrt{v_z^2 + v_\theta^2 + v_r^2}$. The kinetic energy flux factor at the fan outlet is thus equal to

$$\alpha_{eFC} = \frac{1}{v_{FC}^3 A_{FC}} \iint_{A_{FC}} v_z (v_z^2 + v_\theta^2 + v_r^2) dA_{FC} \quad (7)$$

Equation (7) can be decomposed into components so that $\alpha_{eFC} = \alpha_{eFCz} + \alpha_{eFC\theta} + \alpha_{eFCr}$. Near the design point of a free-vortex axial flow fan, the radial velocity is negligibly small so that $\alpha_{eFCr} \approx 0$. The axial component is given by

$$\alpha_{eFCz} = \frac{1}{v_{FC}^3 A_{FC}} \iint_{A_{FC}} v_z^3 dA_{FC} \quad (8)$$

and the tangential component is given by

$$\alpha_{eFC\theta} = \frac{1}{v_{FC}^3 A_{FC}} \iint_{A_{FC}} v_z v_\theta^2 dA_{FC} \quad (9)$$

The minimum value for α_{eFCz} is equal to unity whereas the minimum value for $\alpha_{eFC\theta}$ is zero.

Equations (7) to (9) together with equation (5) show how a diffuser or stator recovers pressure: If a stator can eliminate the swirl exiting the fan, then $\alpha_{edif} \approx \alpha_{eFC} - \alpha_{eFC\theta} \approx \alpha_{eFCz}$. Note that $\alpha_{eFC} = 1.45$, $\alpha_{eFC\theta} = 0.26$ and $\alpha_{eFCz} = 1.20$ for the M-fan at the design point. With a diffuser, α_{edif} and K_{dif} are both functions of the area ratio. The aim would thus be to find a diffuser with the largest possible area ratio which yields reasonably undistorted discharge velocity profiles (for a low α_{edif} -value) and a low total pressure loss, K_{dif} .

Substituting equation (5) into equation (2) produces the following form of the draught equation which can be used to determine the operating point of the ACC, i.e.

$$\Delta p_{Fs} + K_{rec}\rho v_{FC}^2/2 = \Delta p_{sys} \quad (10)$$

The theoretical maximum operating flow rate, \dot{V}_{max} , would occur if $K_{rec} = \alpha_{eFC}$. In this case, the available pressure would be equal to the fan total pressure rise, i.e. $\Delta p_{Ft} = \Delta p_{Fs} + \alpha_{eFC}\rho v_{FC}^2/2$. However, $\alpha_{edif} \geq 1$ due to continuity, AR is limited by diffuser stall, and $K_{dif} > 0$ due to viscous and local losses. The available pressure will, therefore, lie somewhere between the extremes of the static and total pressures, as depicted in figure 2.

From figure 2 it can be seen that pressure recovery will shift the operating point to a higher volume flow rate, \dot{V}_{op} , compared to the initial design flow rate, \dot{V}_{des} . The increased airflow rate allows for higher heat removal rates in the ACC. Smaller overall plant structure sizes might, therefore, be possible due to pressure recovery. In addition, if it is assumed that the power characteristics of the fan remain unchanged after adding a diffuser or stator, the static efficiency of the fan system will increase. This assumption is not without merit as Terzis *et al.* [10] found that the power consumption of a small fan did not change after adding outlet guide vanes.

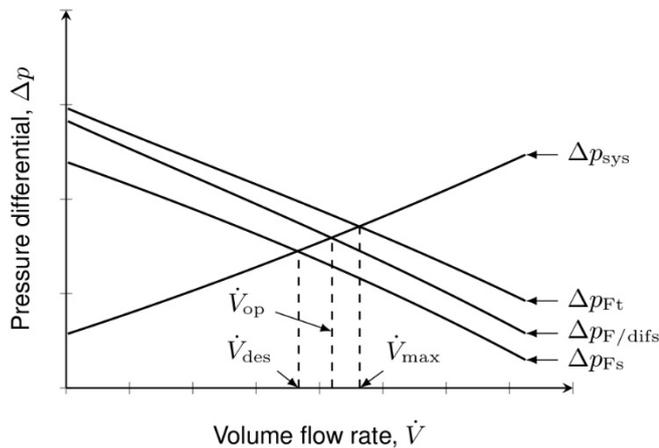


Figure 2: Effect of pressure recovery on the pressure characteristics of the fan.

3 Numerical Modelling

The current investigation employed the open-source CFD code, OpenFOAM 5.0. It was used to solve the Reynolds-averaged Navier-Stokes equations for steady incompressible turbulent flows. Simulations that did not involve stator blade rows were computed using the `simpleFoam` solver.

Simulations that involved stator blades were solved using the EADM solver of Engelbrecht [11]. This solver was obtained by incorporating the EADM into OpenFOAM's `buoyantBoussinesqSimpleFoam` solver. The EADM is an axial flow fan model that was developed by Van der Spuy [7] to improve on the original actuator disc model (ADM) of Thiart and Von Backström [12]. These models make use of isolated aerofoil theory to calculate the force exerted by a fan blade on the air. The flow at the leading and trailing edges of the fan blade as well as the blade profile and orientation along the blade span are taken into account. Multiple researchers successfully employed these models to represent axial flow fans [13–16]. However, in this study, the EADM was used to model stationary stator blades downstream of an axial flow fan.

Pressure-velocity coupling was achieved using the SIMPLE algorithm. Gradient terms were discretised with the second-order central-differencing scheme. Bounded second-order linear-upwind and first-order upwind schemes were used for the advection of velocity and turbulence quantities, respectively. Laplacian terms were discretised using linear interpolation and the limited-corrected scheme with a stabilising coefficient of 0.33 for surface-normal gradients.

The pressure equation was solved using a geometric-algebraic multi-grid (GAMG) linear solver. The stabilised preconditioned bi-conjugate gradient (PBiCGStab) linear solver was employed for the velocity and turbulence equations. Pressure was under-relaxed by 0.2, velocity by 0.6 and turbulence variables by 0.7.

The kinematic viscosity and density of air at 20° were used in all simulations, i.e. $\nu \approx 1.5 \times 10^{-5}$ and $\rho \approx 1.2 \text{ kg/m}^3$, respectively. Solutions were deemed converged after the static pressure at the inlet boundary had reached a constant value and the normalised residuals for all equations had reduced to at least 10^{-5} .

4 Numerical Validation

A representative test case with published experimental data was selected to validate the CFD. The modelling strategies that provided the best results were then applied to the M-fan simulations.

4.1 ERCOFTAC conical diffuser

Clausen *et al.* [6] took detailed measurements of a swirling boundary layer developing in a conical diffuser of included angle 20° and area ratio 2.84, depicted in figure 3. This test case became known as the ERCOFTAC conical diffuser and has been the subject of multiple numerical studies [17–21]. The swirl generator produced an inlet swirl profile of a solid-body rotation and near-uniform axial velocity in the core region. The inlet swirl was sufficient to prevent boundary layer separation but insufficient to cause flow reversal at the centreline. The average inlet axial velocity was $U_0 = 11.6 \text{ m/s}$ and the inlet swirl number was $W_{\max}/U_0 = 0.59$, where W_{\max} is the maximum circumferential velocity at the diffuser inlet. The diffuser discharged into the open atmosphere. Mean velocity and turbulent Reynolds stresses were measured in the diffuser along seven traverses normal to the wall. These traverses are illustrated by the dashed lines in figure 3.

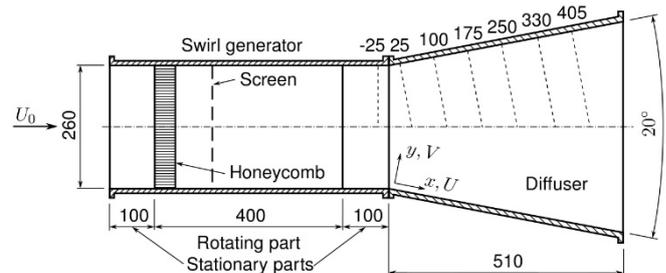


Figure 3: ERCOFTAC conical diffuser with measurement traverses. Dimensions in millimetres. Based on [6].

4.2 Computational setup

The computational domain and boundary conditions are depicted in figure 4. The domain was inspired by that of Gyllenram and Nilsson [18]. However, they used an inlet extension to simulate the effect of the swirl generator, and an outlet extension to direct the flow out of the domain to improve numerical stability. Since experimental data are available at the inlet of the diffuser and numerical stability was not an issue, these inlet and outlet extensions were discarded. The geometry was wedge-shaped in the tangential direction and one cell thick. The wedge angle was five degrees, as recommended by the OpenFOAM user manual [22] for axisymmetric flow problems. The computational mesh comprised of hexahedral elements.

Velocity and turbulence kinetic energy profiles at the inlet (i.e., $x = -25 \text{ mm}$) were interpolated from the experimental measurements of Clausen *et al.* [6]. The inlet pressure boundary condition was set to zero gradient. The diffuser wall was a no-slip boundary with a zero gradient pressure condition. The dump walls were slip walls with zero gradients for all remaining variables. A total pressure boundary condition of zero was specified at the outlet along with zero gradients for velocity and turbulence quantities. The

axisymmetric planes were set to wedge boundaries, which are essentially cyclic boundaries.

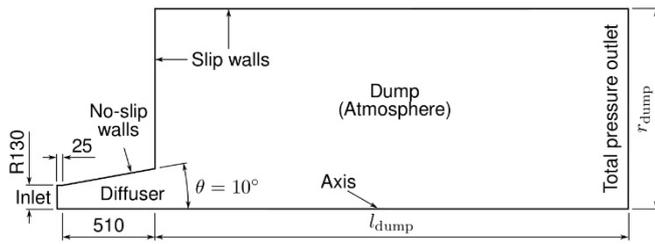


Figure 4: Computational domain and boundary conditions for the ERCOFTAC conical diffuser. The domain is wedge-shaped with an angle of five degrees.

4.3 Sensitivity studies

Various sensitivity studies were performed. These included the sensitivity to grid density, boundary distances, and inlet turbulence quantities. High- and low-Reynolds-number turbulence models were tested, and finally transient and three-dimensional effects were investigated.

The realisable $k-\varepsilon$ model of Shih *et al.* [23] with standard wall functions was used for the initial sensitivity studies. The turbulence dissipation rate at the inlet was computed with

$$\varepsilon = \frac{C_\mu k^2}{\nu(\mu_t/\mu)} \quad (11)$$

where $C_\mu = 0.09$, $\nu = 1.5 \times 10^{-5}$ and $\mu_t/\mu = 14.5$. The latter turbulent viscosity was adopted from Bonous [19].

4.3.1 Grid dependence

For the grid dependence study, the dump length, l_{dump} , and radius, r_{dump} , were fixed to ten diffuser inlet diameters and five diffuser outlet radii, respectively. Five grids with 13 040 to 208 640 nodes were tested for which the location of the first grid point in the diffuser ranged between $y^+ = 22 \sim 115$. The static pressure coefficient of the diffuser and flow profiles at the $x = 330$ mm traverse for the successively refined meshes were compared. With a grid of 104 565 nodes and $y^+ \approx 30$, solutions were deemed to be grid-independent.

4.3.2 Boundary distance effects

The solutions were relatively insensitive to the dimensions of the discharge dump. Dump lengths of four to 14 diffuser inlet diameters were tested with a constant dump radius of five diffuser outlet radii. Dump radii ranging from one to seven diffuser outlet radii were tested with a constant dump length of ten diffuser inlet diameters. A dump with a length equal to eight diffuser inlet diameters and radius equal to five diffuser outlet radii produced boundary-distance independent solutions.

4.3.3 Inlet turbulence quantities

The sensitivity to inlet turbulence quantities was tested using different turbulent viscosities and length scales. The inlet turbulent dissipation rate for the realisable $k-\varepsilon$ model can be computed with equation (11) or

$$\varepsilon = C_\mu^{3/4} k^{3/2} / l_t \quad (12)$$

where l_t is the turbulent length scale. Turbulent viscosity ratios of 14.5 and 27.3 as well as a turbulent length scale of 3.2 mm were tested. These viscosity ratios were adopted from Bonous [19]. The length scale was used by Gyllenram and Nilsson [18] and is equal to the cell size of the honeycomb in the swirl generator. Solutions were affected by the specified inlet turbulent viscosity ratios and length scale. The results computed with the length scale of $l_t = 3.2$ mm compared the closest with the experimental measurements of Clausen *et al.* [6].

4.3.4 Turbulence models

Various turbulence models were tested. High-Reynolds-number models employed standard wall functions at no-slip boundaries. Liu [24] explains the implementation of these wall functions in OpenFOAM. The dimensionless distance from the wall was kept in the order of $y^+ \sim 30$. The tested $k-\varepsilon$ based models included the standard [25], realisable [23], renormalized group (RNG) [26], and quadratic [27] versions. The standard [28] and shear-stress transport (SST) [29] $k-\omega$ models were also tested. Two Reynolds-stress models (RSMs), namely the LRR [30] and SSG [31] models, were added to the investigation. The above models produced the streamwise velocity and turbulent kinetic energy profiles at the last measuring traverse (i.e., $x = 405$ mm) shown in figure 5. As in agreement with the findings of Dhiman *et al.* [20], the SST $k-\omega$ model performed very poorly.

For the low-Reynolds-number models, near-wall grid clustering allowed for integration through the viscous sublayer so that $y^+ \sim 1$. Wall functions were thus avoided. At no-slip boundaries, the turbulence kinetic energy was explicitly set to zero. The $k-\varepsilon$ models that were tested included that of Launder and Sharma [32] as well as the cubic non-linear version of Lien *et al.* [33]. The turbulence dissipation rate, however, still required a wall function to describe the behaviour $\varepsilon = 2\nu k/y^2$ as $y \rightarrow 0$. The wall-integrated standard and SST $k-\omega$ models were also tested. Since the frequency ω tends to infinity at the wall, a large value (i.e., $\omega = 10^{10} \text{ s}^{-1}$) was specified at the wall. Finally, the modified four-equation $\overline{v'^2}$ - f model of Lien and Kalitzin [34] with the limit of Davidson *et al.* [35] was included in the investigation. At the wall, $\overline{v'^2}$ and f were set to zero. Figure 6 contains the distributions at the last measuring traverse for these models. The SST $k-\omega$ model again clearly performed the worst.

It is difficult to make a conclusive statement as to which of the tested turbulence models performed the best. Multiple studies demonstrated that $k-\varepsilon$ models with or without wall functions are incapable of resolving the flow in diffusers [36–39]. Wall functions are generally not applicable in adverse pressure gradients [28], and damping functions lack a sound physical basis [40]. The more sophisticated four- and six-equation models do not show any clear advantage for this flow scenario. The wall-integrated $k-\omega$ model was therefore selected: its results compare fairly well with the

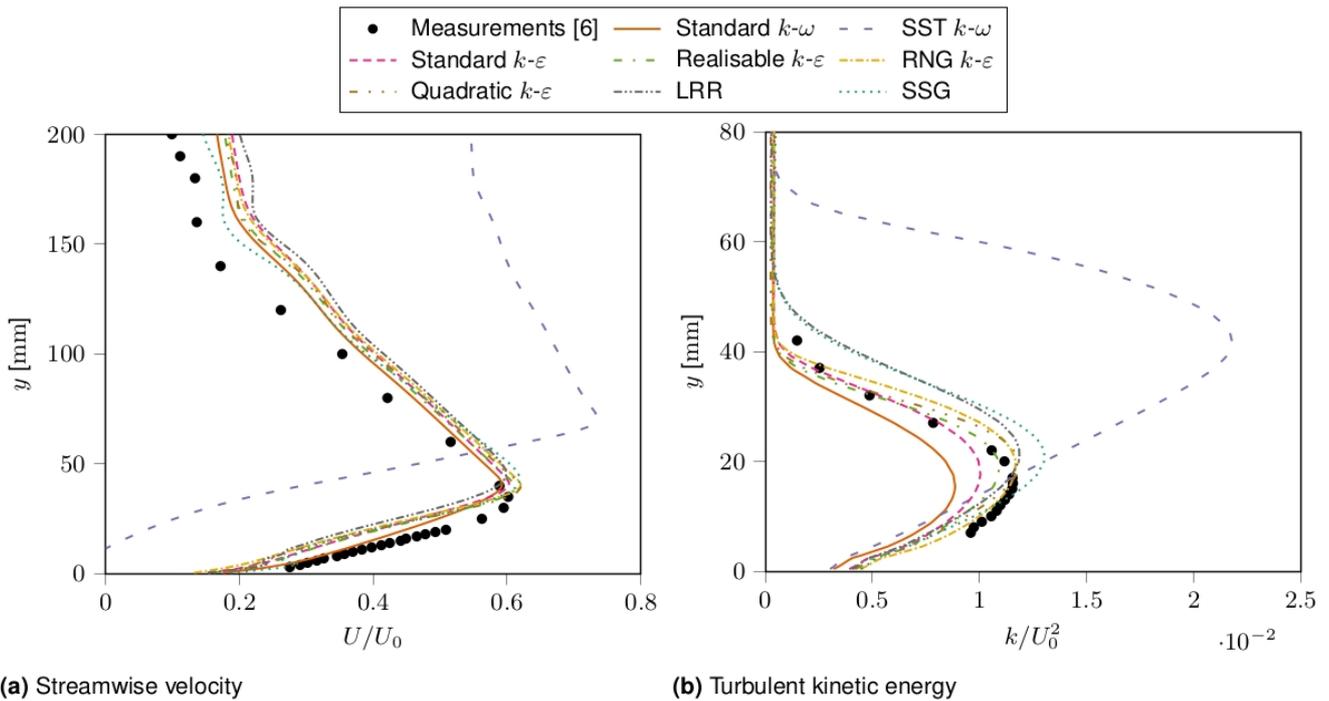


Figure 5: Flow profiles at the $x = 405$ mm traverse for different high-Reynolds-number turbulence models.

measurements and it does not require wall or damping functions.

4.3.5 Transient and three-dimensional effects

The final check was to determine whether the axisymmetric boundary condition and the steady-state assumption eliminated physical aspects of the problem. Both transient

and steady-state simulates were performed on two-dimensional axisymmetric and three-dimensional meshes. Contrary to the findings of Dhiman *et al.* [20], the results of these four cases were essentially the same. Consequently, steady-state axisymmetric simulations were deemed sufficient.

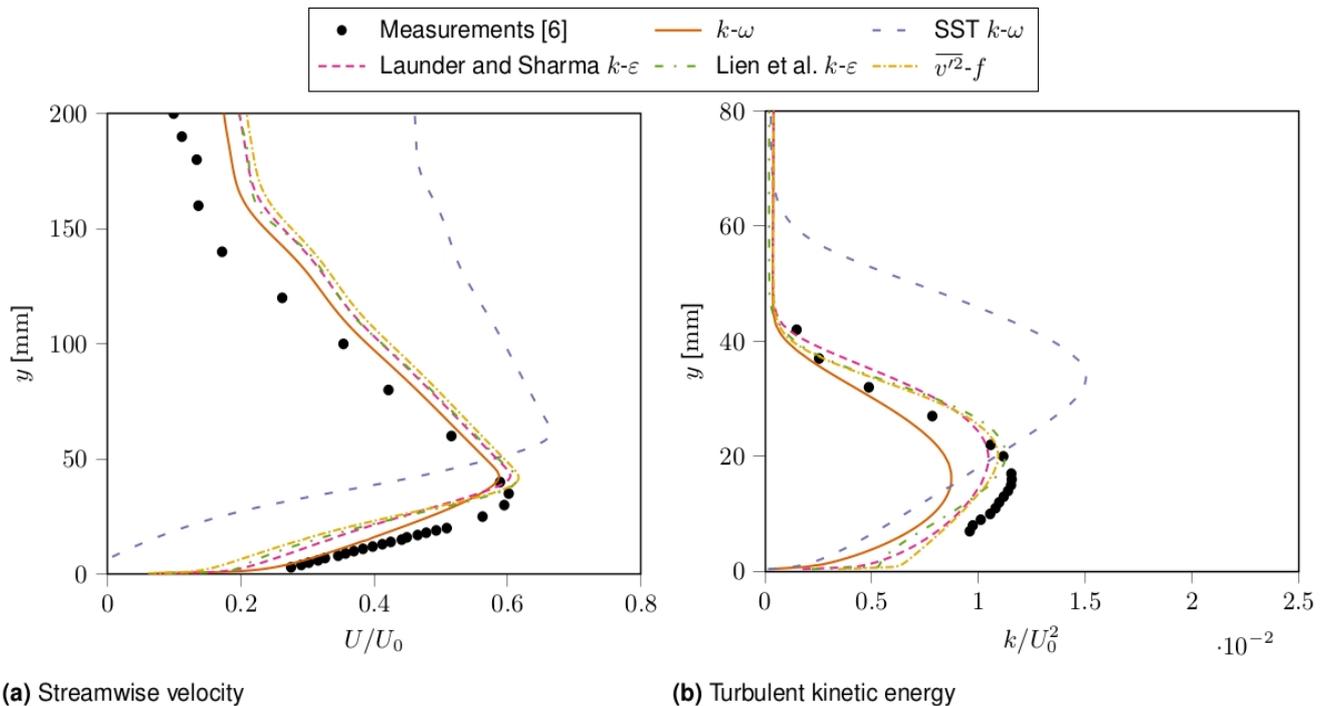


Figure 6: Flow profiles at the $x = 405$ mm traverse for different low-Reynolds-number turbulence models.

5 M-Fan Discharge Configurations

Diffusers, stator blade rows, or a combination of these can convert a portion of dynamic pressure into static pressure, i.e. recover pressure. Various outlet configurations were tested for the M-fan to find the configuration that provides the highest pressure recovery at design and off-design flow rates. The following discharge configurations were tested: a stator alone, conical and annular diffusers with and without stators at their inlets, and an annular diffuser with a stator at its outlet. Finally, the pressure recoveries of the best performing configuration were added to the characteristics of the M-fan to obtain the fan-diffuser characteristics.

5.1 Computational setup

The computational setup and solver settings were similar to those of the validation study. The wall-integrated $k-\omega$ turbulence model was used for all simulations with $y^+ \sim 1$ at no-slip boundaries. Solutions that were deemed independent of the mesh density and the dimensions of the discharge dump were found for each of the different discharge configurations.

The inlet of the computational domain started at the outlet of the M-fan. The fan itself was thus not modelled. Fixed velocity and turbulence profiles at the fan outlet were used to specify the inlet boundary conditions. Circumferentially averaged outlet profiles for the M-fan at flow rates ranging from 260 to 380 m³/s were obtained from Wilkinson [41]. He measured these profiles from the hub to the tip of a periodic three-dimensional CFD model, approximately 0.1 m downstream of the fan blade trailing edge at the hub. Since Wilkinson [41] used the realisable $k-\varepsilon$ turbulence model, the turbulence dissipation rate had to be converted to turbulence frequency using $\omega = \varepsilon/(\beta^*k)$, where $\beta^* = 0.09$ [42].

5.2 Stator details

The stator blade rows were designed using the isolated aerofoil methodology outlined in Louw *et al.* [43]. The stator row at the outlet of the M-fan had nine blades and a mean chord length of 1.286 m. It was located at a half mean stator chord length downstream of the M-fan, as recommended by Wallis [4]. This stator was capable of removing all the swirl exiting the M-fan.

The discharge configuration with a stator row at the outlet of an annular diffuser had to have more stator blades and could only remove a portion of the swirl in order to obtain realistic chord lengths. The stator row had 13 blades with a chord length that varied between 1.29 m at the hub to 1.52 m at the tip. It could only remove 45 % of the swirl.

5.3 Method

Similar to Walter *et al.* [3], it was decided to fix the diffuser length equal to the diameter of the fan. Parametric studies were performed at the design flow rate of the M-fan: The diffuser area ratio was changed by varying the opening angle of the diffuser. For configurations with conical diffusers, the half-wall angle (angle measured between the diffuser wall and axial direction) was varied within the range of $0^\circ \leq \theta \leq 20^\circ$ in increments of one degree. Various combinations of inner and outer half-wall angles were tested for the annular diffusers: The inner half-wall angle was varied in the range of $0^\circ \leq \theta_i \leq 30^\circ$ in increments of two degrees;

a range of outer half-wall angles, θ_o , was tested for each one of these inner wall angles. Approximately 90 simulations were necessary to find the annular diffuser geometry that provides the highest pressure recovery.

The recovered pressure was obtained by subtracting the area-weighted average of the inlet pressure, p_{inlet} , from the outlet pressure, p_∞ . Subsequently, the pressure recovery coefficient was computed with

$$K_{rec} = \frac{p_\infty - p_{inlet}}{\rho v_{FC}^2 / 2} \quad (13)$$

5.4 Results

5.4.1 Pressure recoveries for different discharge configurations

The diffuser geometries that produced the highest pressure recoveries at the design flow rate of the M-fan are summarised in table 2. After the best geometries were found for the design flow rate, they were tested at off-design flow rates. Figure 7 presents the results. Near the design flow rate, the annular diffusers with and without a stator at their inlets perform similarly. However, at lower off-design flow rates, the annular diffuser alone produces higher pressure recovery coefficients. This diffuser is thus recommended for the M-fan since it provides good pressure recoveries at both design and off-design flow rates.

Table 2: Diffuser geometries that produced the highest pressure recoveries at the design flow rate. A constant diffuser length equal to the diameter of the M-fan was used.

Diffuser arrangement	Half-wall angle
Conical	$\theta = 5^\circ$
Conical with stator at inlet	$\theta = 8^\circ$
Annular	$\theta_i = 22^\circ, \theta_o = 22^\circ$
Annular with stator at inlet	$\theta_i = 0^\circ, \theta_o = 14^\circ$
Annular with stator at outlet	$\theta_i = 22^\circ, \theta_o = 22^\circ$

5.4.2 Effect of pressure recovery on fan characteristics

Figure 2 illustrated how pressure recovery could shift the operating point to a higher volume flow rate than the initial design flow rate. The pressure recovery data for the recommended 22° equiangular annular diffuser were added to the characteristics of the M-fan to obtain the combined fan-diffuser characteristics. Figures 8 and 9 depict the fan-diffuser static pressure and static efficiency characteristics, respectively. A system curve of the form $\Delta p_{sys} = a\dot{V}^2$ that passes through the origin and the design point was included in figure 8. The static efficiencies were computed with $\eta_{Fs} = \Delta p_{Fs} \dot{V} / P_F$ and $\eta_{F/difs} = \Delta p_{F/difs} \dot{V} / P_F$, where P_F is the fan power consumption and $\Delta p_{F/difs} = \Delta p_{Fs} + K_{rec} \rho v_{FC}^2 / 2$.

Pressure recovery raised the static pressure from 114.7 Pa at the initial design point to 130.0 Pa at the new operating point, i.e. a 13.3 % relative increase. The flow rate through the fan increased from 333.0 to 354.2 m³/s, i.e. a 6.3 % relative increase. The static efficiency at the new operating point is 79.4 %. This is 20.0 % (absolute) higher than the static efficiency of 59.4 % at the initial design point.

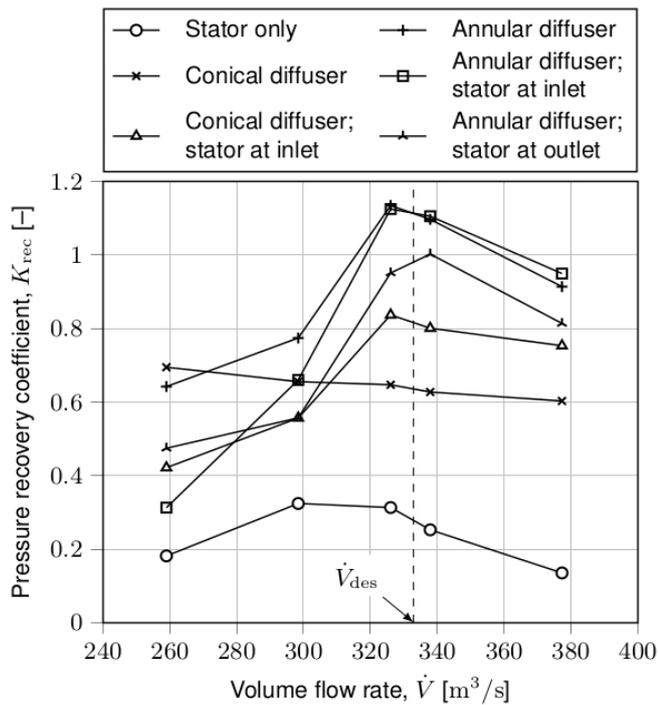


Figure 7: Variation of pressure recovery coefficient with volume flow rate for different outlet configurations. Lines added for clarity; not to indicate trends.

6 Conclusions

This paper outlined the theory of pressure recovery for an induced draught fan arrangement and provided pressure recovery data for various fan discharge configurations. A pressure recovery coefficient, K_{rec} , was introduced into the draught equation. It represents the pressure that is recovered within the discharge diffuser, stator, or diffuser-stator combination.

For numerical validation, CFD was used to simulate the swirling flow in the ERCOFTAC conical diffuser. Steady-state simulations on two-dimensional axisymmetric computational grids proved sufficient. Results were sensitive to the specified inlet turbulence quantities. Various high-Reynolds-number turbulence models with standard wall functions were tested as well as low-Reynolds-number models with integrated boundary layers. The results obtained with the wall-integrated $k-\omega$ model compared reasonably well with experimental measurements. The SST $k-\omega$ model performed poorly, with or without wall functions.

The validated CFD approach was then used to simulate six different discharge configurations for the M-fan in an induced draught arrangement. These included a downstream stator, conical and annular diffusers with or without stators at their inlets, and an annular diffuser with a stator at its outlet. An equiangular annular diffuser without a stator produced the highest pressure recovery coefficients over a range of flow rates. It had wall angles of 22° from the axial direction and a length equal to the diameter of the M-fan, i.e. 7.3152 m.

With a system curve of the form $\Delta p_{sys} = a\dot{V}^2$, the pressure recovery achieved with the equiangular diffuser increased the volume flow rate through the M-fan by 6.3 % (relative). The static efficiency at the new operating point was 79.4 %. This is 20.0 % (absolute) higher than the efficiency at the initial design point of the fan.

This study demonstrated that significant gains in fan performance are available through pressure recovery. However, the costs associated with pressure recovery installations have limited their application in practice. With the rising costs of energy, pressure recovery devices might become a valuable proposition for fan industries in the future.

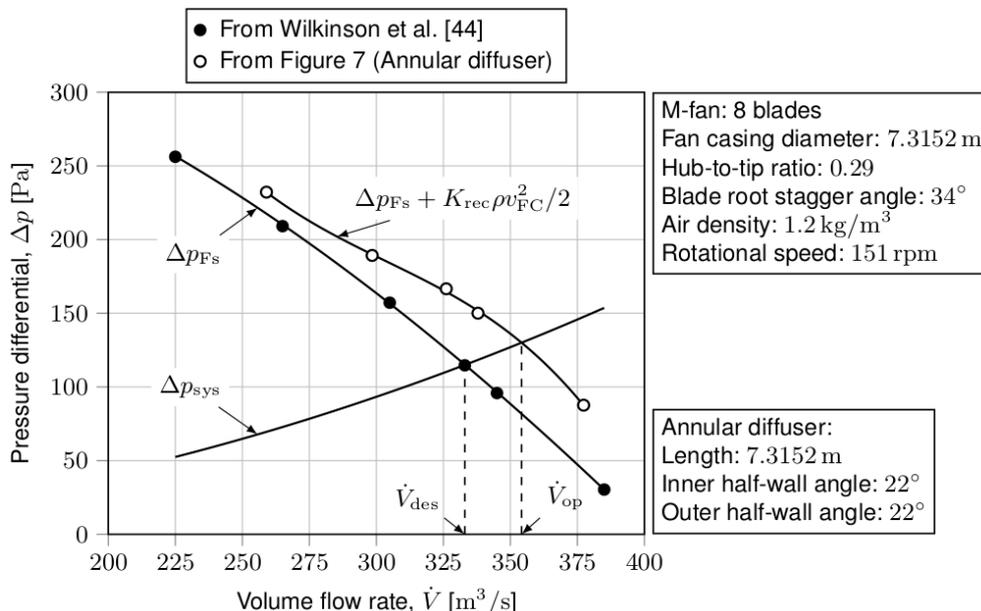


Figure 8: Effect of pressure recovery on the M-fan pressure characteristics.

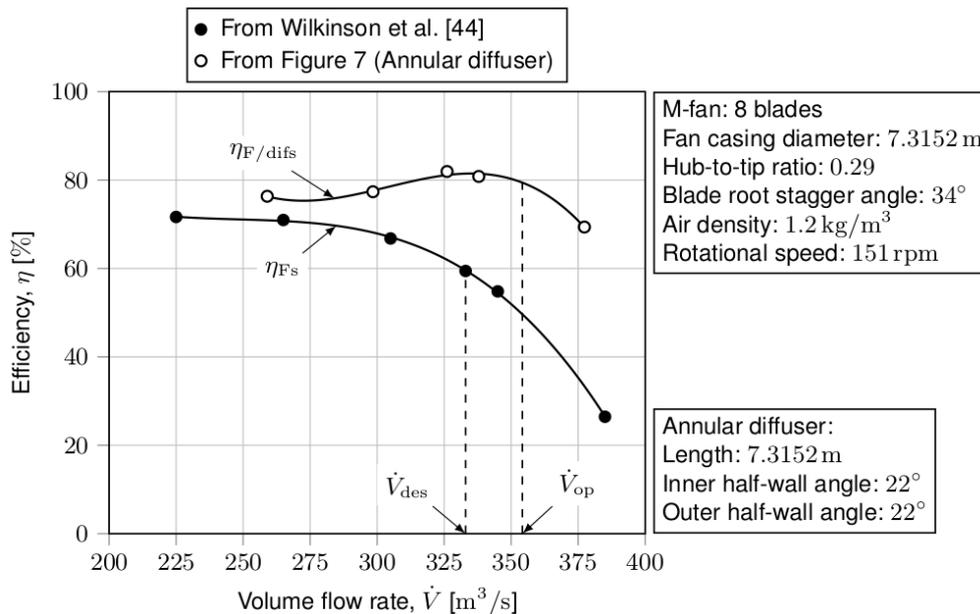


Figure 9: Effect of pressure recovery on the M-fan efficiency characteristics.

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