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2D Linear Galerkin finite volume analysis of thermal stresses during sequential layer settings of mass concrete considering contact interface and variations of material properties

Part 1: Thermal analysis

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In this research, a new explicit 2D numerical solution is presented to compute the temperature field which is caused due to hydration and thermal conductivity by the Galerkin finite volume method on unstructured meshes of triangular elements. The concrete thermal properties vary, based on the temperature variation and the age of the concrete in the developed model. A novel method for imposing natural boundary conditions is introduced that is suitable for the Galerkin finite volume method solution on unstructured meshes of triangular elements. In addition, the thermal contact is considered at the concrete-rock foundation interface to achieve more realistic simulations in this section. In this work we present the comparison of the thermal analysis numerical results of a plane wall, which had different thermal boundary conditions applied to its edges, with its analytical solution to assess the accuracy and efficiency of the developed model. The applicability of the developed numerical algorithm for thermal analysis is presented by the solution of thermal fields during gradual construction of a typical mass concrete structure.

INTRODUCTION

Gradual setting of concrete layers during construction of mass concrete structures may give rise to drastic temperature gradients due to the cement hydration and heat conduction properties of the concrete. Cement is a basic ingredient of concrete which, by the process of hydration, mixes with aggregates and water and produces concrete. This process is exothermic and causes the concrete temperature to rise. After achieving maximum temperature, the temperature decreases until it reaches the ambient temperature. Predicting the temperature field resulting from the concrete hydration process during a particular construction programme is an important consideration in the design and construction of mass concrete structures like concrete dams. However, the thermal properties of concrete (specific heat and thermal conductivity) vary according to the concrete temperature and the degree of concrete hydration. These changes can be considered in the thermal analysis of the

mass concrete structures by the adoption of available empirical relationships.

The finite volume method has been widely applied to heat transfer and fluid dynamic problems through relatively simple discretisation (Vaz Jr *et al* 2009). In recent years the finite volume method has been used for the solution of temperature analysis, stress-strain computations and thermal stress solutions of solid mechanical problems, some of which are listed in the following review.

For the computation of temperature fields, an unstructured finite volume node-centered formulation was implemented, using an edge-based data structure for the solution of two-dimensional potential problems (Lyra *et al* 2002). Lyra *et al* used an edge-based unstructured finite volume procedure for the thermal analysis of steady state and transient problems (Lyra *et al* 2004). Recently, a 2D finite volume method to solve a heat diffusion equation was developed to predict the transient temperature field in an RCC (roller-compacted concrete)

dam wall during concreting of sequential layers, taking into consideration the constant thermal properties during concrete setting (Sabbagh–Yazdi *et al* 2007).

The variation in concrete properties significantly influences the prediction of the temperature history of mass concrete structures. Much research has been done to calculate temperature fields, and different numerical models have been used in the various solution methods to simulate the temperature field in mass concrete structures. For example, a 2D finite difference method for predicting the hydration-induced temperature profile in mass concrete was developed, considering a sinusoidal function for the surrounding air changes (Ballim 2004).

A 3D finite element solution was proposed for thermal analysis by Kim *et al* (2001) who considered the effect of pipe cooling systems. Ilc *et al* (2009) also developed a numerical model for the thermal analysis of young concrete structures, based on the finite element method. Considering the constant thermal properties of concrete, the **NASIR** (Numerical Analyzer for Scientific and Industrial Requirements) concrete temperature solver, a 2D finite volume method solver for heat generation and transfer equation, was developed to predict the transient temperature field in an RCC dam wall during sequential layers of concrete setting (Sabbagh–Yazdi *et al* 2001). The accuracy and efficiency of the proposed model were assessed by comparing the numerical results from the analysis with analytical solutions for problems with constant concrete properties and various boundary conditions (Sabbagh–Yazdi *et al* 2007). In this research, the variation in the heat conduction properties of concrete that occurs due to changes in concrete temperature and the ageing process is considered in terms of the **NASIR** concrete temperature solver. For this purpose, a 2D matrix-free Galerkin finite volume solution is utilised for computing the temperature fields in mass concrete structures on unstructured meshes of triangular elements. In the developed numerical model, the heat generation and transfer equation is explicitly solved to compute the temperature field. For the cases where the boundary normal vector is parallel to the direction of the grid in the coordinate system, it is easy to impose the natural gradient boundary condition. To overcome the difficulties that may appear when imposing such a boundary condition at inclined boundaries of unstructured meshes of triangular elements, a technique is applied in this work to modify the gradient flux vectors at the centre of the boundary elements. This method is adopted for the implementation of the natural gradient

boundary condition for the solution of heat generation and transfer equation using the Galerkin finite volume method.

HEAT GENERATION AND TRANSFER MATHEMATICAL MODEL

Heat transfer mathematical model

The heat generation and transfer equation is produced from different thermodynamics and heat transfer references (Sabbagh–Yazdi *et al* 2007).

$$\left[\frac{\delta}{\delta x} \left(k_x \frac{\delta T}{\delta x} \right) + \frac{\delta}{\delta y} \left(k_y \frac{\delta T}{\delta y} \right) \right] + \dot{Q} = \rho C \dot{T} \quad (1)$$

where k (J/m.h.°C) is the thermal conductivity of concrete, T (°C) is concrete temperature, \dot{Q} (J/m³.h) is the rate of heat generation per volume, ρ (kg/m³) is the density of concrete, and C (J/kg.°C) is the specific heat of concrete.

The two main boundary conditions at the external surfaces are:

$$T = T_{\text{air}}, \quad k \frac{dT}{dN} = -q \quad (2)$$

where T_{air} (°C) and q (w/m²) are the air temperature and the rate of heat exchange.

$$q = \pm q_c + q_r - q_s$$

$$q_c = h_c (T_{\text{surface}} - T_{\text{air}}), \quad h_c = h_n + h_f, \\ h_n = 6 \text{ (w/m}^2 \cdot \text{°C)}, \quad h_f = 3.7V \text{ (w/m}^2 \cdot \text{°C)}$$

$$q_r = h_r (T_{\text{surface}} - T_{\text{air}})$$

$$q_s = \gamma \cdot I_N \quad (3)$$

where q_c , q_r and q_s are heat flux by convection, long wave radiation and solar radiation, respectively; h_n , h_f and h_r are natural, forced and radiation convection; and $\gamma \cdot I_N$ (w/m²) and V (m/s) are surface absorption, incident normal solar radiation and wind speed, respectively.

In this research, the effects of long wave radiation and solar radiation in heat flux have been disregarded and the wind speed has been supposed to be zero.

Cement hydration heat generation

Cement is a basic ingredient of concrete which gains its cementitious property after mixing with water. This chemical reaction called hydration causes the paste to harden and gain strength. Because of its significance, several research efforts into the concrete heat of hydration field and the appropriate mathematical models, have already been presented (Noorzaei *et al* 2006; Riding 2007).

In general, hydration is a thermo-activated reaction, and temperature primarily affects

the rate of hydration. Hence, the equivalent age parameter and maturity function are used to consider this feature. Through the maturity function, the effect of concrete temperature on the rate of hydration is regarded.

Equation 4 is used to calculate the heat of hydration.

$$Q(t_e) = A + E \cdot \exp(-b \cdot (t_e)^{-n}) \quad (4)$$

where A , E , b , n are variables which are calculated by appropriate fitting of Equation 4 to experimental data, and t_e (hr) is the equivalent age.

By adopting the Rastrup maturity function, the following equation is used to calculate the equivalent age:

$$H(T) = 2^{0.1(T-T_{\text{ref}})}, \quad t_e = \int H(T) dt \quad (5)$$

where $H(T)$, T , T_{ref} (°C), are the relative speeds of hydration reaction, concrete temperature and reference temperature, respectively.

Finally, Equation 6 is used to calculate the rate of concrete hydration (Sabbagh–Yazdi *et al* 2007):

$$\dot{Q}(t_e) = n \cdot b \cdot E \cdot (t_e)^{-n-1} \cdot \exp(-b \cdot (t_e)^{-n}) \cdot 2^{0.1(T-T_{\text{ref}})} \quad (6)$$

The hydration process is a long-term reaction, with different hydration products developing over time as a result of the chemical reaction of water with the cement components. Through this process, a skeleton of hardened cement paste is formed. Due to the ageing process, therefore, the concrete properties (thermal and mechanical) may change during the hydration reaction. The degree of hydration is equivalent to the amount of heat liberated at any point during the hydration stage to the total heat corresponding to the end hydration. Many different relationships are presented to calculate the degree of concrete hydration. One of these models is the Schindler model, in which the degree of hydration is calculated by the mixture proportions and the concrete age, as presented in Equation 7.

$$\alpha_{\text{con}}(t_e) = \alpha_u \cdot \exp\left(-\left(\frac{\tau}{t_e}\right)^\beta\right) \quad (7)$$

where α_u (unitless) is the ultimate degree of hydration, τ is hydration time parameter, t_e (hr) is the equivalent age, and β is the hydration slope parameter. The fit parameters (α_u , τ , β) are specified according to the mixture proportions (Schindler 2004).

Using Equation 7, the rate of heat generation due to the concrete heat of hydration can be represented by the source terms, heat generation and transfer equation. In addition, the

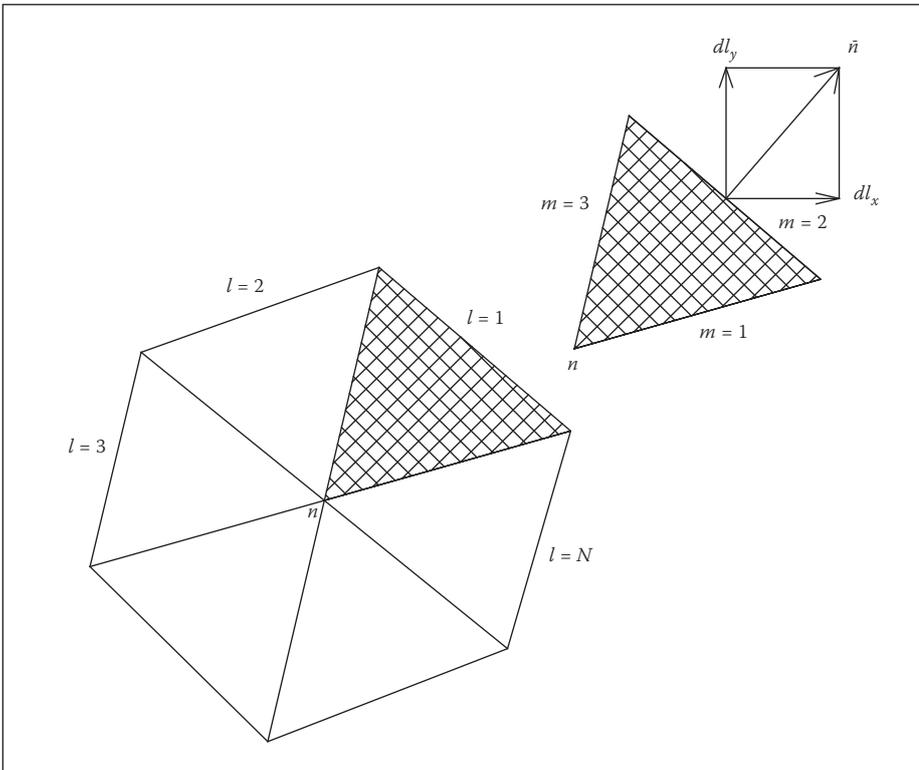


Figure 1 Triangular element within the subdomain Ω_n

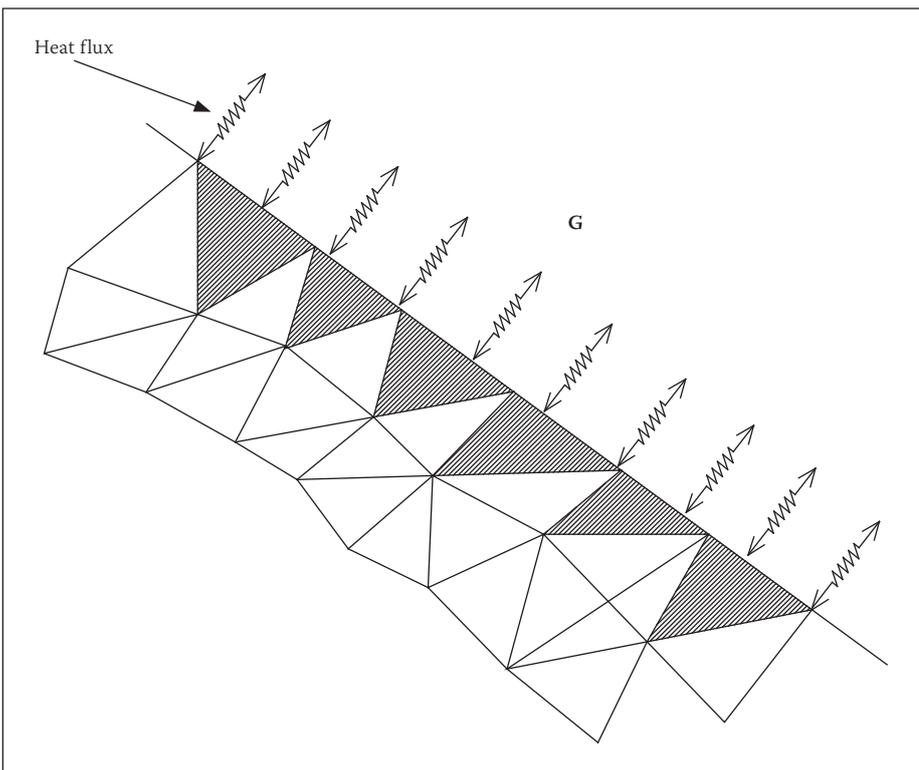


Figure 2 Triangular elements of the boundary edge

variation of concrete thermal properties (such as specific heat and thermal conductivity) during the ageing process can be considered in the computational thermal analysis.

Ageing effects on thermal properties of concrete

The concrete temperature and degree of concrete hydration affect the thermal properties of the concrete. The relationships below, which are related to change in the thermal

properties of concrete over time, are used in the present thermal analysis.

Specific heat

The specific heat of concrete, which is equal to the required heat for 1°C increase of concrete temperature per unit mass of the concrete, depends on the mixture proportions, the degree of hydration, concrete temperature and the relative humidity of concrete.

The following equation is used for changes in the specific heat of concrete over time, as provided by Van Breugel (1998):

$$C = \frac{1}{\rho}(w_c \alpha_{con} c_{ref} + w_c(1 - \alpha_{con})c_c + w_a c_a + w_w c_w) \quad (8)$$

$$C_{ref} = 8.4 T + 339$$

where C (J/kg.K) is the specific heat of concrete; ρ (kg/m³) is the density of concrete; w_c , w_a , w_w (kg/m³) are the weight of cement, aggregate and water per unit volume; c_c , c_a , c_w (J/kg.K) are the specific heat of cement, aggregate and water respectively; α_{con} is the degree of concrete hydration; and T (°C) is the concrete temperature.

Thermal conductivity

The thermal conductivity of concrete, which is the concrete's ability to conduct heat, represents the amount of heat transition through a unit thickness of concrete in a direction normal to a surface area at the unit time. This parameter is dependent on the relative humidity, type and amount of aggregate, porosity and the density of the concrete.

Schindler (2002) stated that a higher degree of hydration decreases the thermal conductivity of concrete. The following equation was proposed by Schindler:

$$k(\alpha_{con}) = k_{ue}(1.33 - 0.33\alpha_{con}) \quad (9)$$

where k (w/m.K) is the transient thermal conductivity, k_{ue} (w/m.K) is the ultimate thermal conductivity of concrete, and α_{con} is the degree of concrete hydration.

NUMERICAL SOLUTION

Galerkin finite volume formulations

The heat generation and transfer Equation 5 can be written as:

$$\left(\frac{\delta}{\delta x_i} F_i^H\right)_n + \left(\frac{\alpha}{k} \dot{Q}\right)_n = \left(\frac{\delta T}{\delta t}\right)_n \quad (i = 1,2) \quad (10)$$

where F_i^H is diffusive flux in i direction.

$$F_i^H = \alpha_n \frac{\delta T}{\delta x_i}, \quad \alpha_n = \left(\frac{k}{\rho C}\right)_n \quad (11)$$

In each time step, the values of thermal properties (k , C) are updated considering the concrete temperature and degree of concrete hydration. Then the source term (S_n) is computed for every node (n) of the concrete body.

By application of the Galerkin weighted residual method, after multiplying the residual of Equation 10 by a weight function (which can be considered as the nodal shape function of a linear triangular element, ϕ_n) and integrating over a subdomain Ω_n (which

is formed by gathering all the elements sharing node n), the weighted integral form of Equation 10 is written as Equation 12:

$$\int_{\Omega} \left(\frac{\delta F_i^d}{\delta x_i} \right) \phi_n d\Omega + \int_{\Omega} \left(\frac{\alpha \dot{Q}}{k} \right)_n \phi_n d\Omega = \int_{\Omega} \left(\frac{\delta T}{\delta t} \right)_n \phi_n d\Omega \quad (12)$$

The weak form of Equation 12, after the omission of zero boundary terms, is expressed as:

$$-\int_{\Omega} (F_i^H \cdot \nabla \phi_n) d\Omega + \int_{\Omega} \left(\frac{\alpha \dot{Q}}{k} \right)_n \phi_n d\Omega = \int_{\Omega} \left(\frac{\delta T}{\delta t} \right)_n \phi_n d\Omega \quad (13)$$

The approximate ratio given in Equation 14 can be used to calculate the spatial derivative term of Equation 13:

$$\int_{\Omega} (F_i^H \cdot \nabla \phi_n) d\Omega \approx \frac{1}{2} \sum_{k=1}^3 (\bar{F}_i^H \cdot \bar{\Delta l}_i)_k \quad (14)$$

Here $(\bar{\Delta l}_i)_k$ is the i direction component of the normal vector of edge k of the subdomain Ω_n which is opposite to its central node n (Figure 1).

The source term of the Equation 13 can be approximated as:

$$\int_{\Omega} \left(\frac{\alpha \dot{Q}}{k} \right)_n \phi_n d\Omega \approx \frac{\Omega_n}{3} \left(\frac{\alpha \dot{Q}}{k} \right)_n \quad (15)$$

Using the forward differencing method, the discrete form of the transient term of the governing equations can be written as follows:

$$\int_{\Omega} \left(\frac{\delta T}{\delta t} \right)_n \phi_n d\Omega = \left(\frac{T_n^{t+\Delta t} - T_n^t}{\Delta t} \right)_n \frac{\Omega_n}{3} \quad (16)$$

The explicit form of the heat generation and transfer equation for subdomain Ω_n is expressed as Equation 17:

$$T_n^{t+\Delta t} = T_n^t + (\Delta t)_n \left[\frac{3}{2\Omega_n} \sum_{i=1}^N (\bar{F}_i^H \cdot \bar{\Delta l}_i)_i^t + \left(\frac{\alpha \dot{Q}}{k} \right)_n^t \right] \quad (17)$$

where $T_n^{t+\Delta t}$ is temperature of node n at time $t+\Delta t$, and N is the number of edges surrounding the subdomain Ω_n (Figure 1).

Computation of heat flux vector components

The components of the heat flux vector

$$F_i^H = \alpha_n \frac{\delta T}{\delta x_i}$$

must be calculated at the centre of the elements corresponding to the boundary edges of the subdomain Ω_n (Figure 1).

The integration over an element can be converted to a boundary integral using the Gauss divergence theorem:

$$\int_{\Omega_E} \frac{\delta T}{\delta x_i} d\Omega = \oint_1 T_i \cdot dl_i \quad (18)$$

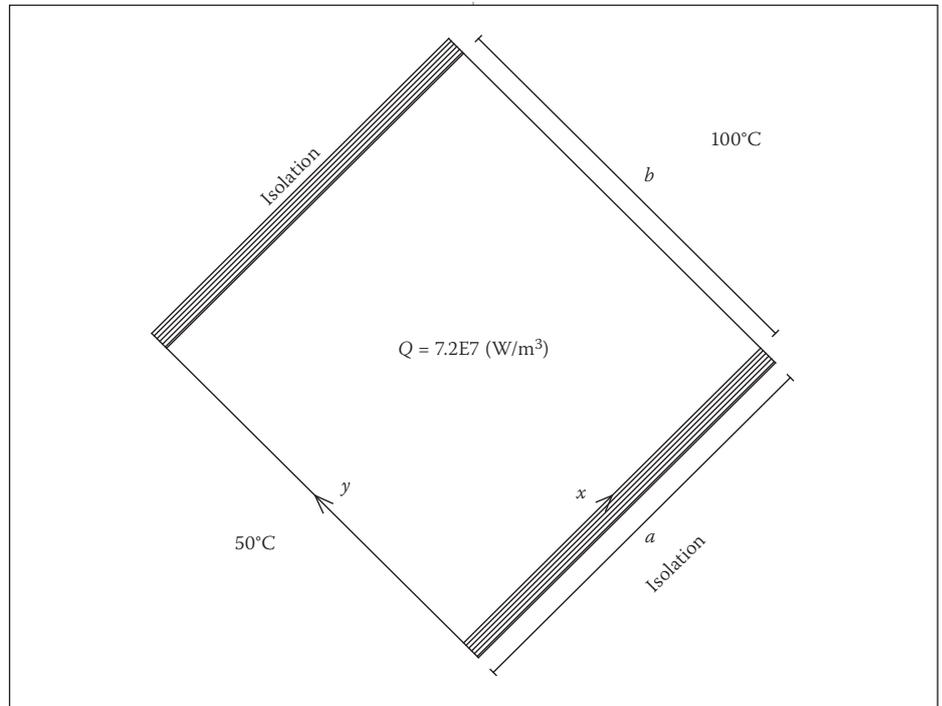


Figure 3 Schematic illustration of plane wall

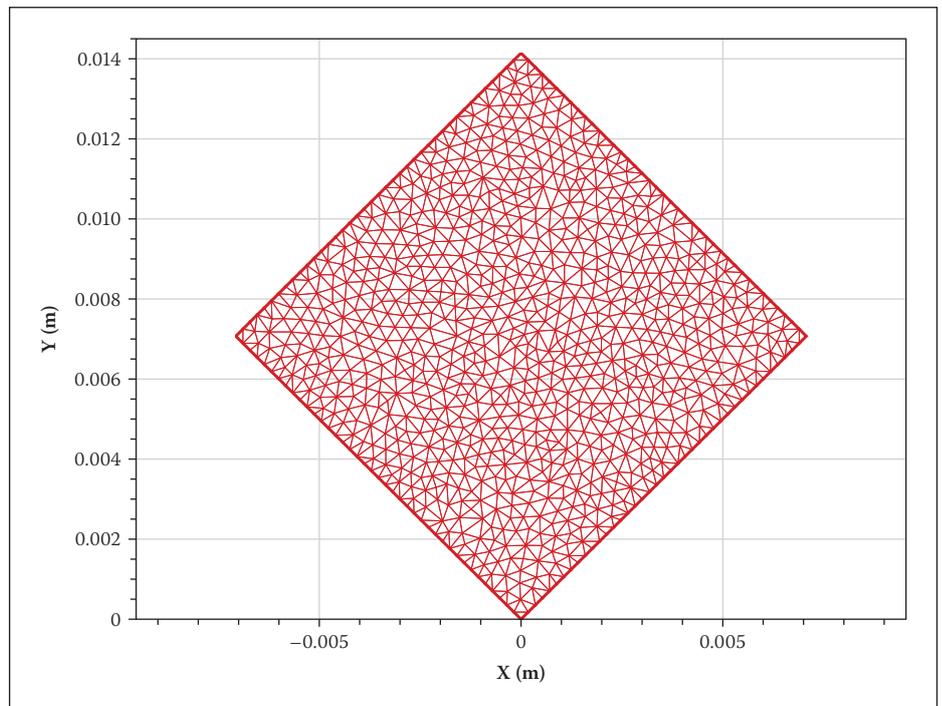


Figure 4 Unstructured meshes of triangular elements for thermal analysis (with 940 nodes and 1 718 elements)

where Ω_E is the area of a triangular element. The discrete form of the line integral can be written as:

$$\oint_1 T_i \cdot dl_i \approx \frac{1}{\Omega_E} \sum_{m=1}^3 (\bar{T} \cdot \Delta l_i)_m \quad (19)$$

where Δl_i is the component of the m^{th} edge normal vector of a triangular element which is perpendicular to the i direction, and \bar{T} is the average temperature at the same edge (Figure 1).

Hence, diffusive flux at each triangular element for both directions can be calculated using the following equation:

$$\begin{aligned} (F_x^H) &= \left(\alpha_n \frac{\delta T}{\delta y} \right) \cong \frac{1}{\Omega_E} \sum_{m=1}^3 (\bar{T} \cdot \Delta l_y)_m \\ (F_y^H) &= \left(\alpha_n \frac{\delta T}{\delta x} \right) \cong \frac{1}{\Omega_E} \sum_{m=1}^3 (\bar{T} \cdot \Delta l_x)_m \end{aligned} \quad (20)$$

Boundary conditions

Two types of boundary conditions, known as essential and natural boundary conditions, are usually applied in thermal analysis.

The essential and natural boundary conditions are used for certain temperature and temperature gradient flux at boundaries, respectively.

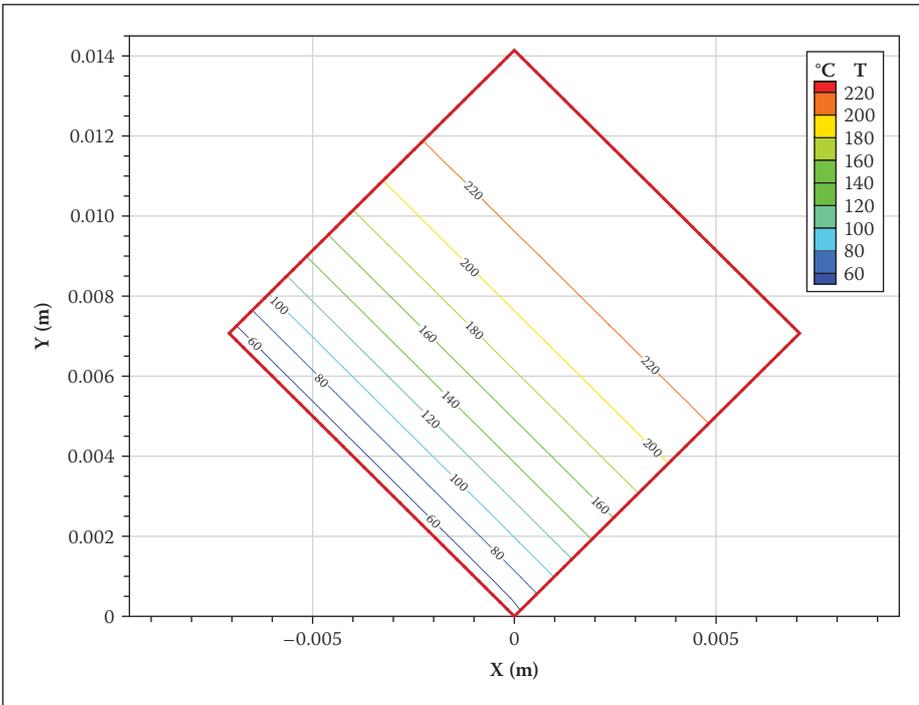


Figure 5 Computed temperature contours

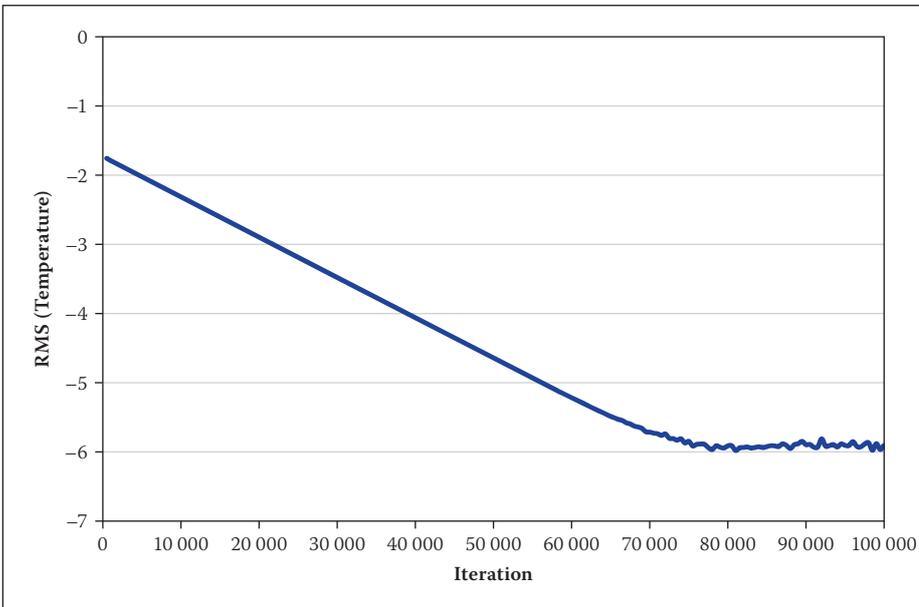


Figure 6 Convergence of logarithm of root mean square of temperature

For the cases where the boundary normal vector $\hat{n} = (n_x, n_y)$ is parallel to the direction of the grid in the coordinate system, the given normal gradient due to heat flux by convection, G , can simply be inserted, but the computational difficulties arise for inclined or curved boundaries. To solve this problem, the computed gradient flux vector (Equation 20) at the centre of the boundary elements (hatched elements in Figure 2) at the end of each computational step may be modified as Equation 23.

$$\bar{F}^H = (F_x^H)\hat{i} + (F_y^H)\hat{j} = \left(\alpha_n \frac{\delta T}{\delta x}\right)\hat{i} + \left(\alpha_n \frac{\delta T}{\delta y}\right)\hat{j} \quad (21)$$

$$(\bar{G})_{\text{normal}} = \left(\frac{q_c}{k} n_x\right)\hat{i} + \left(\frac{q_c}{k} n_y\right)\hat{j} \quad (22)$$

$$(\bar{F}^d)_{\text{modify}} = \alpha_n \left(\frac{\delta T}{\delta x} + \frac{q_c}{k} n_x\right)\hat{i} + \alpha_n \left(\frac{\delta T}{\delta y} + \frac{q_c}{k} n_y\right)\hat{j} \quad (23)$$

where k is thermal conductivity and q_c is heat flux by convection, which was defined previously.

Time integration

If the propagation speed of heat is considered proportional to α_n , the critical time step size solution of the heat generation and transfer equation can be written as Equation 24:

$$\Delta t < M \left(\frac{\Omega_n}{\alpha_n}\right) \quad (24)$$

where M is a coefficient that is less than unity.

Table 1 Specifications of plane wall

Height	$b = 1 \text{ cm}$
Thickness	$a = 1 \text{ cm}$
Thermal conductivity	$k = 18(\text{w}/(\text{m} \cdot ^\circ\text{C}))$
Internal heat generation	$Q_0 = 7.2 \cdot 10^7(\text{w}/\text{m}^3)$

In order to maintain the stability of the explicit solution, the minimum time step size of the computational domain must be used in the computation of the unsteady problems. For the steady state cases, the concept of local time stepping can be used where every node has a special time step which reduces the programme execution time.

THERMAL CONTACTS

When two solids, of initially different temperatures, are brought into contact, thermal coupling must be considered within the contact analysis. Heat normally flows from one solid to another one at the interface between the two solids; this affects the temperature distribution near the contact surfaces. A constitutive equation is required for the determination of heat flux in the contact zone. In addition, the heat conduction is dependent on contact pressure in the contact area. The following equation is often assumed to be the constitutive equation for heat flux:

$$q = \bar{h}(T^2 - \bar{T}^1) \quad (25)$$

Where T^2 is the temperature of the slave node and \bar{T}^1 is the temperature of the closest point in the master surface to the slave node. The heat transfer coefficient (\bar{h}) depends on the temperature of the contact surfaces and the contact pressure. The heat transfer can be accomplished in three possible ways, i.e. heat conduction through spots (h_s), gas (h_g) and radiation (h_r). The following equation is obtained when one assumes that the above-mentioned mechanisms act in parallel:

$$\bar{h} = h_s + h_g + h_r \quad (26)$$

In this research, the heat conduction through gas and radiation has been disregarded and Equation 27 is used to determine the heat conduction through the spots in the contact interface.

$$h_s = h^r \left(\frac{P}{H_v}\right)^\xi \quad (27)$$

where P is the contact pressure and coefficients h^r , H_v and ξ are the thermal resistance coefficient, Vickers hardness and an

exponent, respectively, which are given as $h^r = 1.0$, $H_v = 3.0$ and $\xi = 1.5$.

The thermal boundary condition is applied by the following equations for each node in the contact interface:

$$T^2 = T^1, K \frac{dT}{dn} + q = 0 \quad (28)$$

where T^1 and T^2 are the temperature of solids 1 and 2, respectively, and $\frac{dT}{dn}$ and q are the thermal conductivity, normal temperature gradient and heat flux, respectively (Wriggers 2002).

VERIFICATION AND APPLICATION

Verification test

In this section, the solution for a steady state problem with inclined boundary is presented. Using the developed solver, the time stepping limit of the formulation is utilised to maintain the stability of iterative computation from the assumed initial condition towards the steady state condition. Furthermore, use of the local time stepping method speeds up the computation towards equilibrium. Consider a plane wall with specifications as presented in Table 1.

The boundary at $y = 0, b$ of the domain is assumed to be insulated. The boundary at $x = 0$ is maintained at $T_0 = 50^\circ\text{C}$, and the boundary at $x = a$ is exposed to ambient temperature $T_c = 100^\circ\text{C}$ (Figure 3). The film coefficient is $h_c = 200(\text{w/m}^2\text{C})$. The assumption of an insulated boundary condition at $y = 0, b$ of the domain results in the 1D heat flowing along the x direction. In this case, the analytical temperature field is given as Equation 29 (Reddy *et al* 2000).

$$T(x) = 50 + 5 \frac{x}{a} + 200 \left(1.9 - \frac{x}{a} \right) \frac{x}{a} \quad (29)$$

where $x(m)$ is the distance from the edge, which is held at a constant temperature of 50°C , and $a(m)$ is the dimension of the plate.

Unstructured meshes of triangular elements are shown in Figure 4, and computed temperature contours are illustrated in Figure 5.

Using the Dell Vostro 1500 with an Intel Core 2 Duo T7100 CPU with 1.8 GHz, 2 GB main memory, the CPU time measured 44.6 seconds.

The root mean square of the computed temperature during iterations, which is calculated by Equation 30, is shown in Figure 6. In Figure 7 the temperature changes along the x direction are compared with the analytical results. The good correlation between the computed results and the analytical solution is promising.

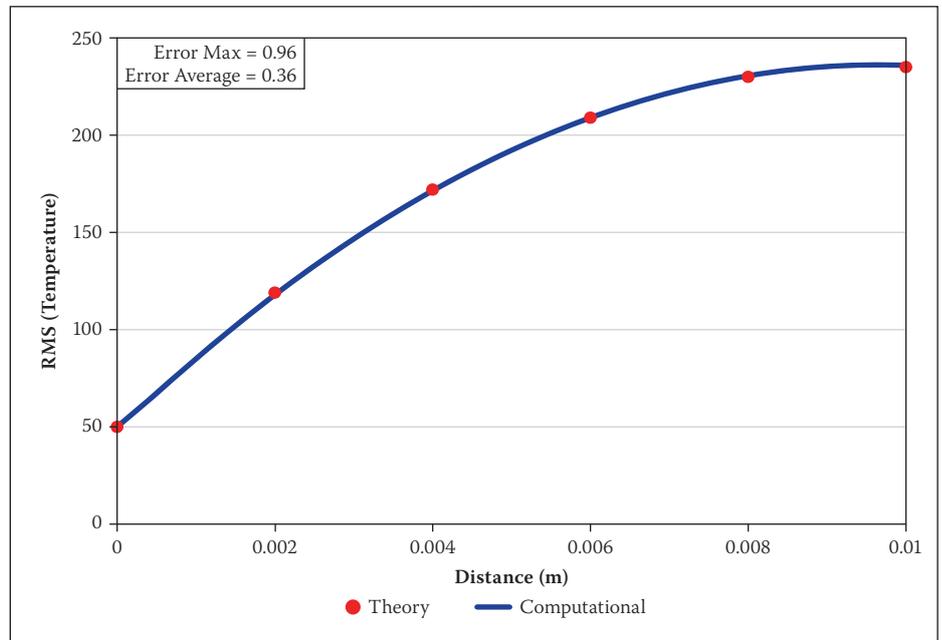


Figure 7 Comparison of computed temperature with analytical solution (along the x-axis)

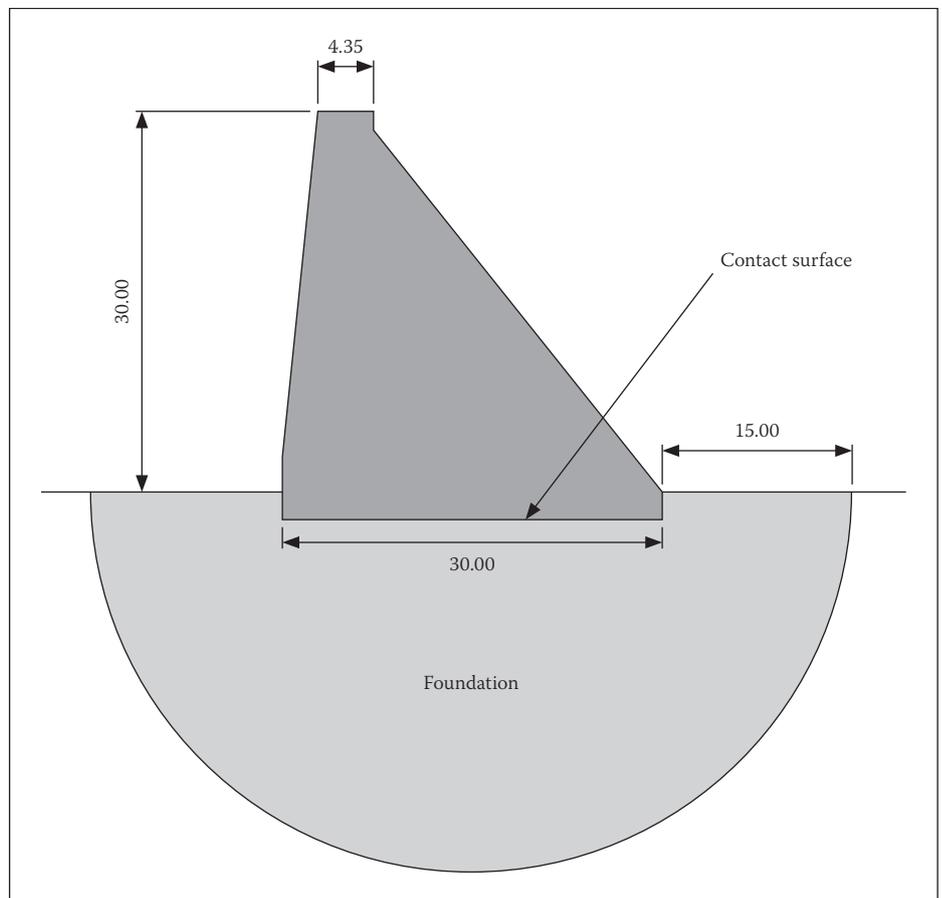


Figure 8 Schematic illustration of a typical mass concrete structure on a natural foundation

$$\text{RMS} = \text{Log} \left(\sqrt{\frac{\sum_{i=1}^N (T_i^{t+\Delta t} - T_i^t)^2}{N}} \right) \quad (30)$$

Application case

In this section, the developed algorithm is utilised to analyse the transient temperature field during the gradual construction of a typical mass concrete structure. The dam is 30 m high, while the base and crest are 30 m and 4.35 m wide, respectively. The left

and right slopes are 0.1:1, 0.8:1 respectively (Figure 8). Layer thickness at every concreting is 0.5 m, and the interval between consecutive concrete placing lasts 48 hours. The portion of the dam foundation that is considered for thermal analysis is shown in Figure 8.

The far field boundary of the foundation is treated as a zero gradient boundary condition, and the Newton thermal boundary condition is used for the external surfaces of the dam wall and ground surface (Figure 8).

The use of unstructured meshes of triangular elements for the geometric modelling of the foundation media (Figure 9) facilitates simulation of the geo-structure layers with irregular formation and material variation. Likewise, application of structured meshes of triangular elements for the dam wall (Figure 9) provides the development of concrete media in the vertical direction (proportional to the construction stage and concrete layer). The sinusoidal function is utilised for air temperature changes.

The thermal properties and mixture proportions of concrete are presented in Tables 2 and 3. The specific heat of materials, which is needed to calculate the specific heat of concrete, is presented in Table 4.

As mentioned, thermal properties of concrete vary with the ageing process. In the present analysis, the relationships as presented above are used for the simulation of the changes in the thermal properties of concrete over time. The thermal properties of the mass concrete structure are summarised in Table 2.

Using the presented relationships, the thermal properties of concrete can be determined according to concrete ageing over time, as shown in Figures 10 and 11. Having the transient changes of the thermal properties, these properties are assigned to each node considering the temperature and age of every concrete layer during thermal analysis. The simulation results for the various stages of gradual construction of a typical mass concrete dam are presented in terms of the transient temperature contour in Figure 12 (see page 102).

CONCLUSION

A 2D matrix-free Galerkin finite volume solution is presented to compute the transient temperature field, considering the variable thermal properties on the developing linear triangular elements due to the heat of hydration and thermal conduction through boundary surfaces during gradual concreting of concrete structures. The represented explicit solution is a computationally efficient algorithm which can achieve results of time-dependent heat generation and transfer problems with considerably low computational effort and CPU time consumption. However, for the steady state problems, the time stepping of the formulation may be utilised for iterative stable computation towards equilibrium, and using the local time stepping method, the programme execution time can be reduced.

Due to the hydration progress of concrete and the ageing process, the thermal properties of concrete vary over time. In

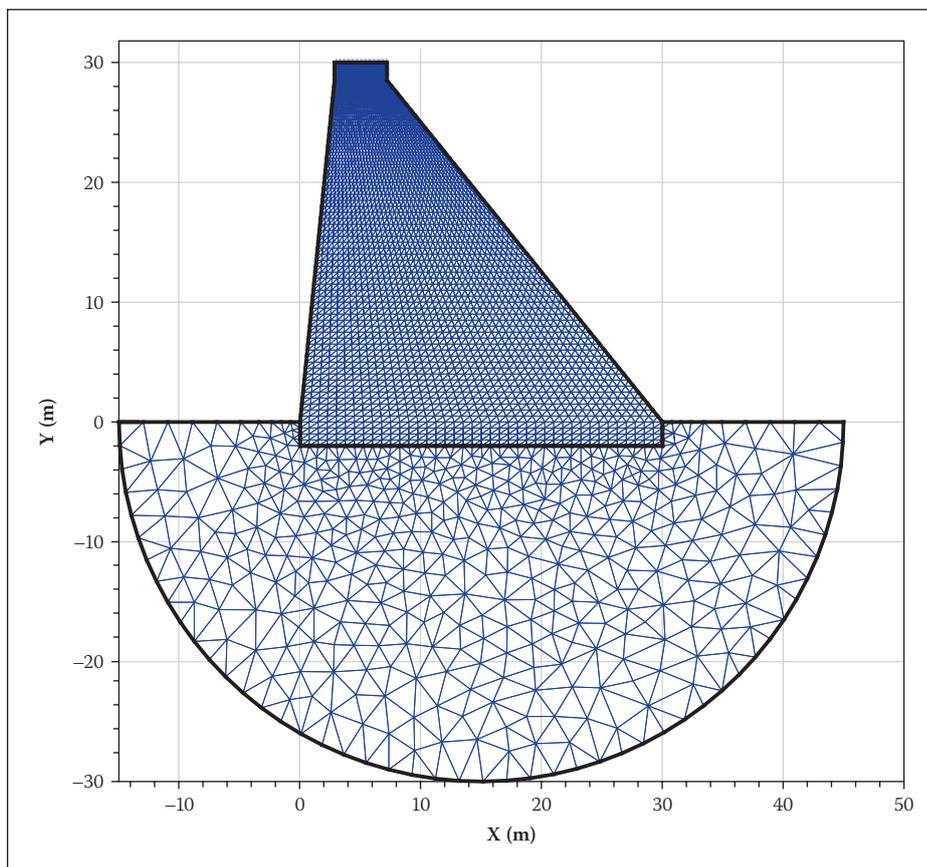


Figure 9 The triangular elements of a typical RCC dam wall

Table 2 Thermal properties of concrete

	Material property	Value
Concrete	Coefficient of thermal expansion	Variable (asymptote value = $10^{-5}/^{\circ}\text{C}$)
	Specific heat	Variable (asymptote value = $827 \text{ J/kg}^{\circ}\text{C}$)
	Thermal conductivity	Variable (asymptote value = $10 \text{ 326 J/m.h}^{\circ}\text{C}$)
Foundation	Thermal conductivity	$9 \text{ 360 J/m.h}^{\circ}\text{C}$
	Thermal diffusivity	$0.0038 \text{ m}^2/\text{s}$

Table 3 Mixture proportions of concrete in a unit volume

Material	Value (kg/m^3)
Cement	150
Aggregate	1 936
Water	163

the present transient thermal analysis of the concrete media, the proposed relationships by previous researchers, as mentioned above, are used for the simulation of the transient changes in the thermal properties of concrete according to concrete temperature and the degree of concrete hydration. The method presented in this research resolves the problem of imposing a normal temperature gradient at the inclined boundaries of unstructured meshes of triangular elements. In the developed algorithm, the temperature gradient boundary condition is applied by the modification of the gradient

Table 4 Specific heat of materials

Material	Specific heat ($\text{J/kg}^{\circ}\text{C}$)
Cement	1 000
Aggregate	800
Water	2 080

flux vector at the centre of the boundary elements.

In addition, the geometry of the dam wall and foundation is not considered integrated anymore, so the thermal contact is considered at concrete-rock foundation interface to achieve more realistic simulations in this part. In this work we present the comparison of the thermal analysis numerical results of a plane wall, where different thermal boundary conditions are imposed at its edges, with its analytical solution to assess the accuracy and efficiency of the developed model. The computed

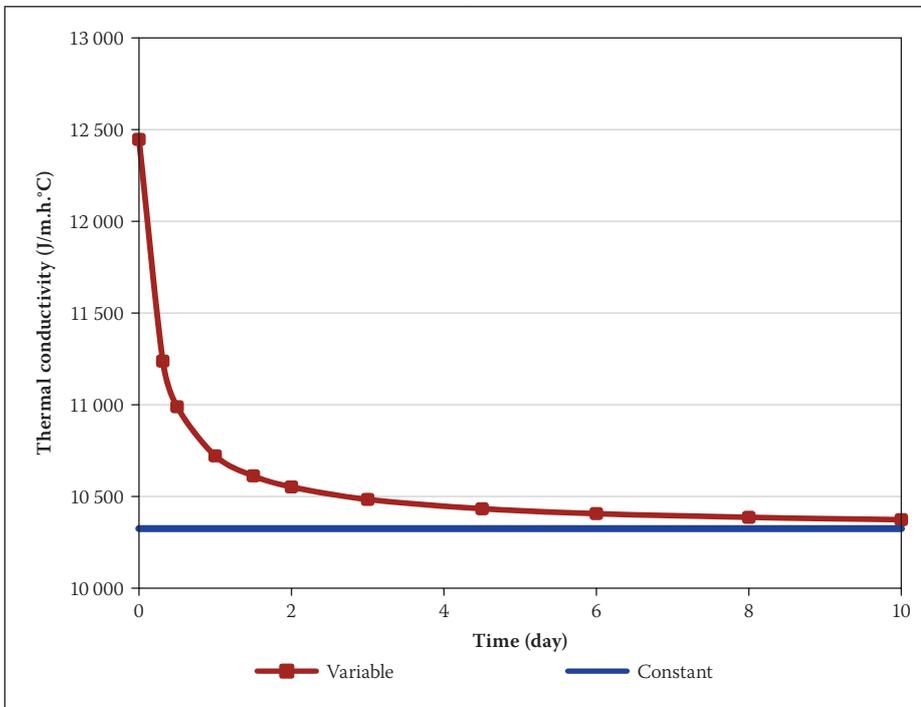


Figure 10 Variation of thermal conductivity during concrete ageing

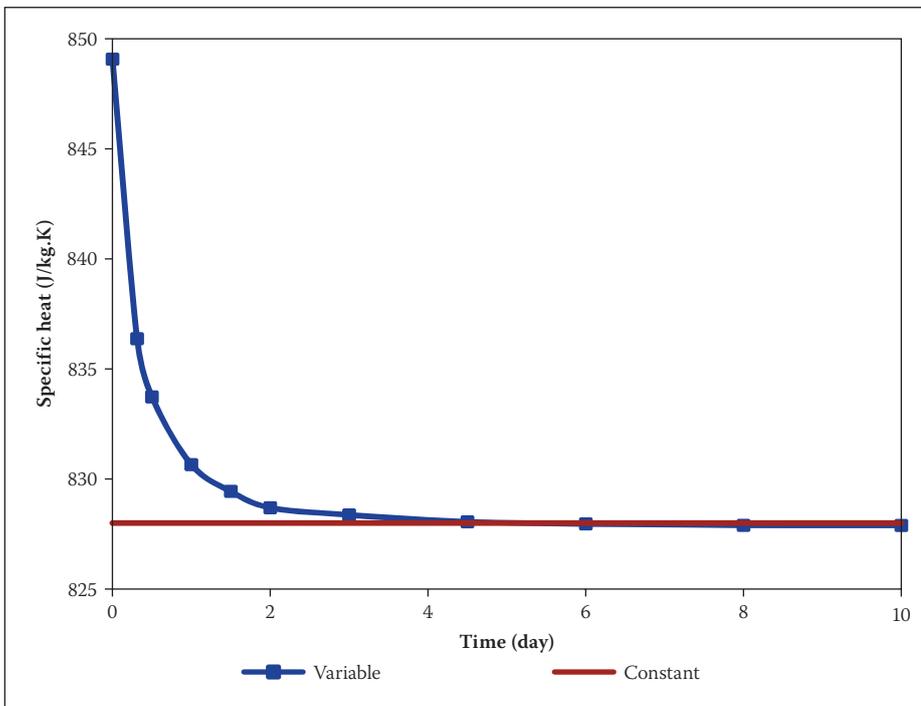


Figure 11 Variation of specific heat during concrete ageing

results presented promising correlation with the analytical solution. In order to present the applicability of the developed solver to simulate real-world problems, the developed model was used for transient thermal analysis of a typical mass concrete structure on a natural foundation in which the concrete media were gradually developed via sequential setting of fresh concrete layers.

The concrete temperature module of the **NASIR** Galerkin finite volume solver can be applied as a useful modelling means for the prediction of transient temperature profiles during the desired sequential construction programme of a mass concrete

structure, considering variations in thermal properties.

NOTATION SECTION

- k : Thermal conductivity of concrete
- k_{uc} : Ultimate thermal conductivity of concrete
- C : Specific heat of concrete
- ρ : Density of concrete
- S_n : Source term
- t_e : Equivalent age of concrete
- T : Concrete temperature
- T_{ref} : Reference temperature
- $T_{surface}$: Concrete surface temperature

- T_{air} : The air temperature
- $T_n^{t+\Delta t}$: Temperature of node n at $t + \Delta t$ time
- \bar{T} : Average temperature of edge
- Q : Heat of hydration
- \dot{Q} : Rate of heat generation per volume
- Q_0 : Internal heat generation
- α_{con} : Degree of concrete hydration
- α_u : Ultimate degree of hydration
- A, E, b, n : Fit parameters
- τ : Hydration time parameter
- β : Hydration slope parameter
- q : Rate of heat exchange
- q_c : Heat flux by convection
- q_r : Heat flux by long wave radiation
- q_s : Heat flux by solar radiation
- h_n : Natural convection
- h_f : Forced convection
- h_r : Radiation convection
- γ : Surface absorption
- I_N : Incident Normal Solar Radiation
- V : Wind speed
- Ω : Subdomain
- $\bar{\Delta l}_i$: Normal component of boundary edge at the i direction for the subdomain Ω
- N : Number of control volume outside faces
- \vec{n} : Normal vector of the boundary edges
- Ω_E : Area of the triangular element
- Δl : Edge of triangular element
- F_i^H : Diffusive flux in i direction.
- G : Given normal temperature gradient
- Δt : Time step size for heat generation and transfer equation
- M : Coefficient that can be considered less than unity
- w_c, w_a, w_w : Weight of cement, aggregate and water, respectively
- c_c, c_a, c_w : Specific heat of cement, aggregate and water, respectively
- h_c : Film coefficient
- x : Distance
- a : Dimension of plate

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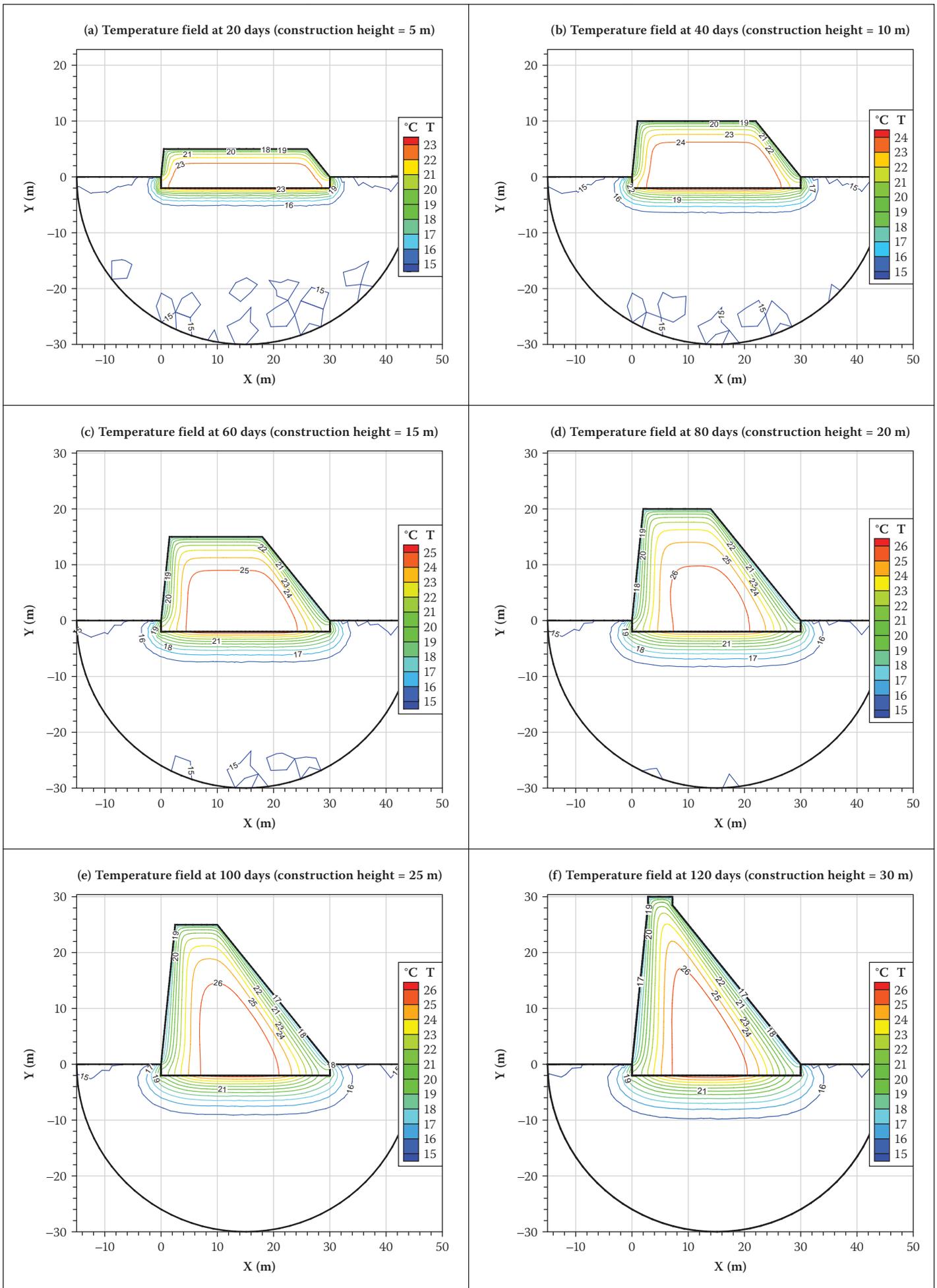


Figure 12 Computed results of temperature distribution for various construction heights, considering variations of thermal properties according to the age of each concrete layer

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